

Immingham Green Energy Terminal

Preliminary Environmental Information Report
Appendix 16.A – Numerical Model Calibration

Associated British Ports

December 2022

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1 Numerical Model Calibration

1.1 Introduction

1.1.1 ABPmer has been commissioned to undertake hydrodynamic, sediment transport, dredge plume and wave studies to support the development and consenting of the Immingham Green Energy Terminal (IGET) within the Port of Immingham. The site for the proposed Terminal lies within the eastern sector of the Port and will facilitate the operation, by multiple users, of a multi-user liquid bulk jetty.

1.1.2 The marine elements of the project comprise:

- a. A new approach trestle;
- b. Jetty platform;
- c. Berthing and mooring dolphins with link walkways; and
- d. Topside infrastructure for the handling of liquid bulks, including loading arms and pipeworks.

1.1.3 To assist with the study, numerical hydrodynamic, wave and sediment transport models have been set up and calibrated or verified. This Appendix provides a description of the modelling tools that have been applied in the assessment and details the setup, calibration and validation of the individual modules. The aim of this exercise is to demonstrate that the modelling tools provide a realistic, representative description of the existing conditions that occur at the site and, consequently, that the model provides a suitable basis to examine the potential impacts associated with the proposed development. The assessment covers hydrodynamic and wave effects, along with changes to the sediment transport regime at the site and the dispersion of material released from the associated dredging operations.

1.1.4 This calibration appendix is sectioned as follows:

- a. Section 1.2: Describes the setup and calibration of the hydrodynamic model;
- b. Section 1.3: Describes the setup of and verification of the sediment transport model;
- c. Section 1.4: Describes the setup of the dredging operations dispersion model; and
- d. Section 1.5: Describes the setup of and verification of the spectral wave model.

1.2 Hydrodynamic Model

1.2.1 The hydrodynamic modelling for this study has been completed using the state-of-the-art Danish Hydraulic Institute (DHI) software package MIKE21FM (Flexible Mesh), which has been developed specifically for applications within oceanographic, coastal and estuarine environments.

- 1.2.2 This project utilises the MIKE21 Hydrodynamic (HD) module to simulate the variations in water level and two-dimensional depth averaged flow within the study area. The model has been set up to examine how the proposed Project will affect the hydrodynamics and, in turn, the sediment regime within this area of the Humber. The model is also used to examine the advection and dispersion of material released from the associated dredging operations.
- 1.2.3 The model setup, calibration and validation are described in the following sections.

Model grid

- 1.2.4 The HD model extent is based on ABPmer's existing numerical model of the region, encompassing the entire Humber Estuary, and an associated area offshore to enable suitable boundary conditions to be applied (Plate A1).
- 1.2.5 The model grid uses the flexible mesh feature of the MIKE 21 software, allowing the grid resolution to vary throughout the model domain. This allows key areas of interest to be covered with a higher resolution grid, increasing the level of detail and precision. Offshore areas are then given a coarser resolution, aiding computational efficiency. Within this model grid, the offshore extents of the Humber, near the model boundaries, have a resolution of approximately 800 m. At the entrance to the Humber, this reduces to approximately 700 m, and continues to reduce through the estuary, reaching a resolution of around 75 m at Hull Bend. At its finest, the grid has a resolution of approximately 20 m around the proposed IGET dredge pocket and berth and the adjacent foreshore and port infrastructure. An overview of the mesh resolution is provided in Plate A1.

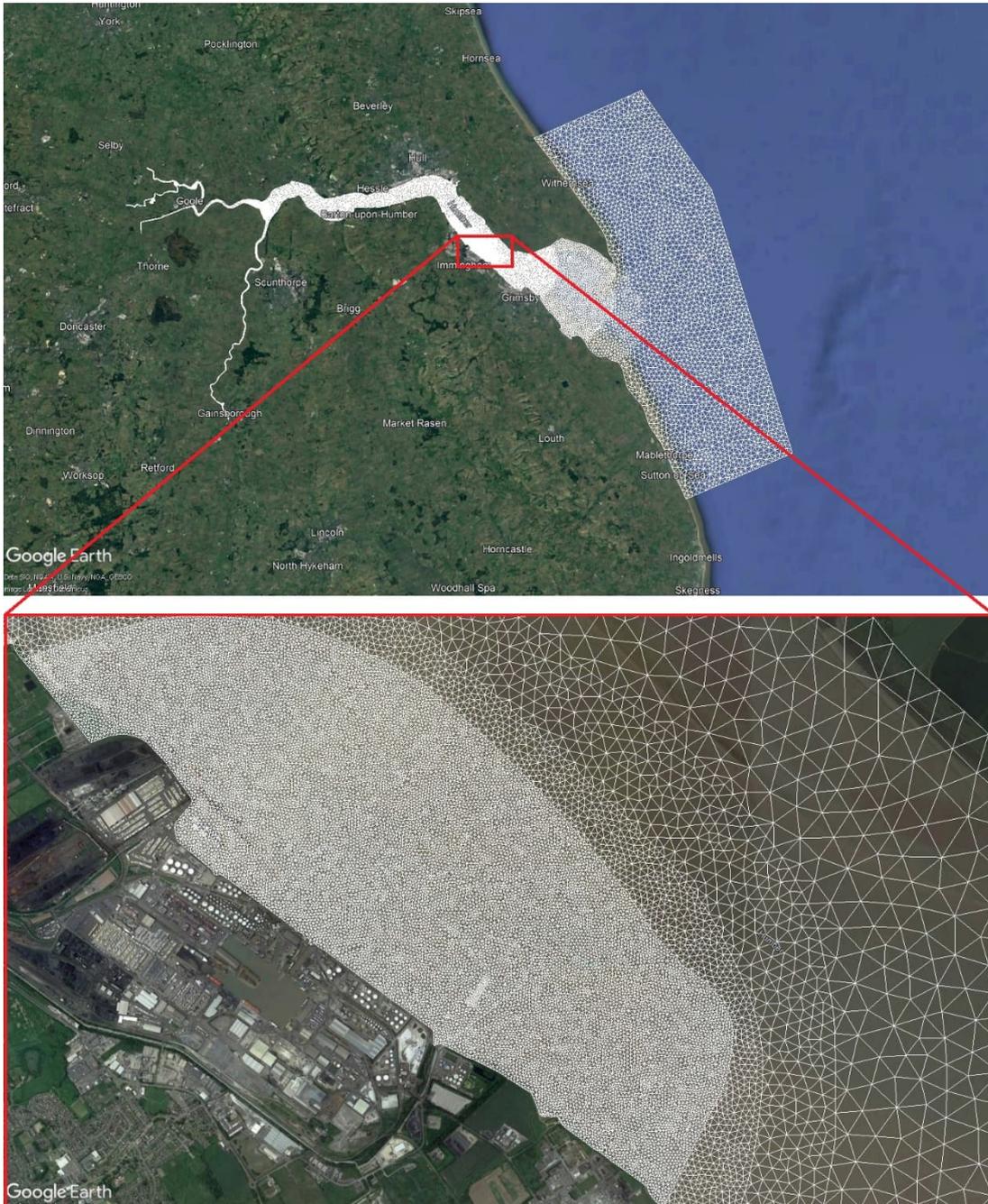


Plate A1. Overall model extent (top), resolution at key area of interest (bottom)

Model bathymetry

- 1.2.6 The bathymetric datasets used in the creation of the model mesh consist of a combination of survey data provided by ABP for the study site and including additional local survey data from ABP Humber Estuary Services (HES). The Project survey campaign is still underway and will be reported upon completion. An overview of the coverage of these data is shown in Plate A2 and Plate A3.

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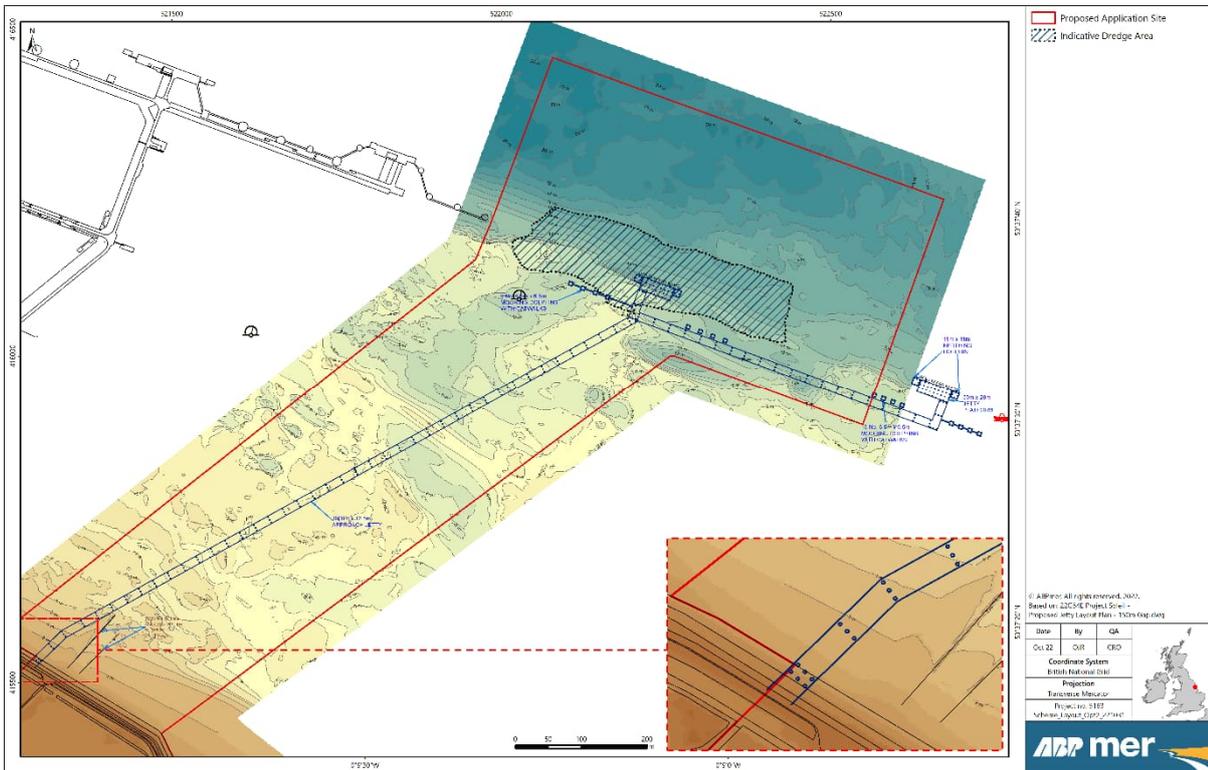


Plate A2. Overview of extent of bathymetry data provided by ABP for the study

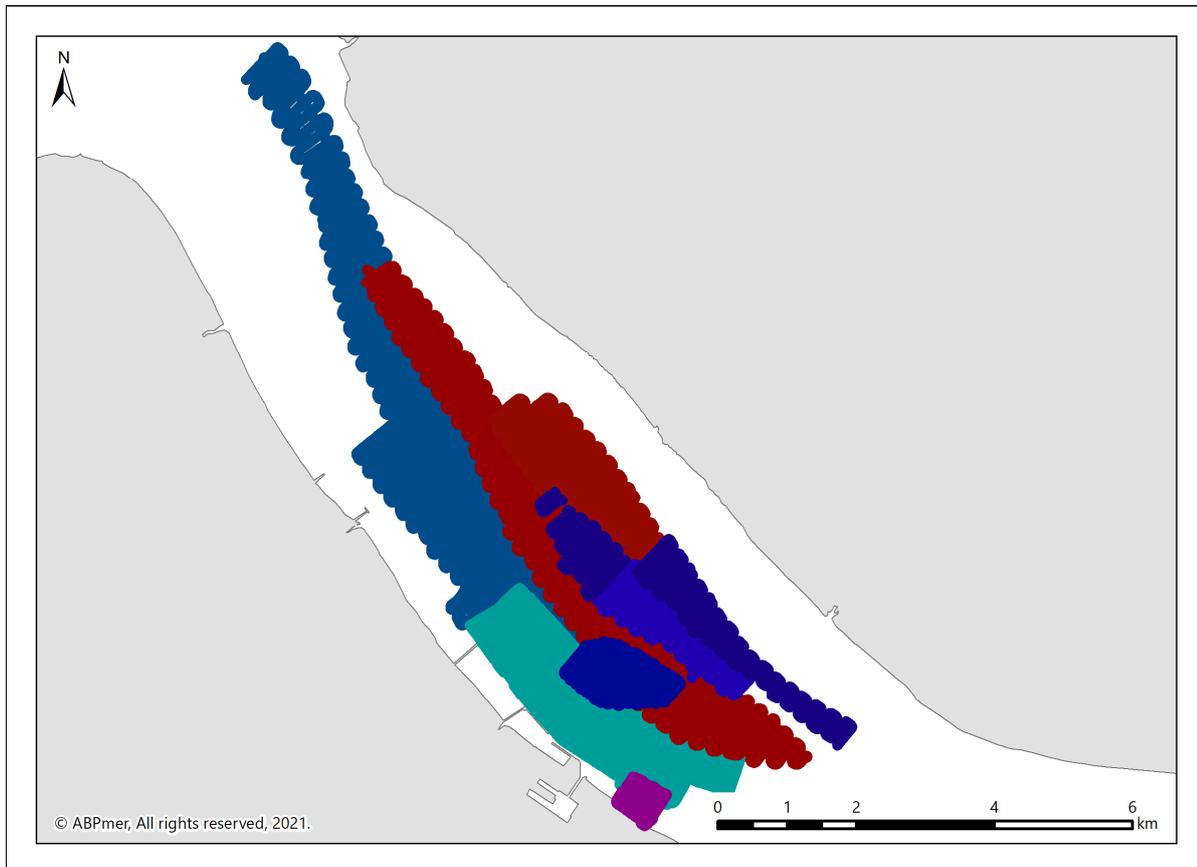


Plate A3. Overview of additional ABP HES bathymetric data used in the model for the study

- 1.2.7 Alongside the project-specific bathymetry data, the model also utilises survey data collected by ABP HES in August 2019 and March, April, and May 2021, covering the area around IOT and main channel (Plate A3). Additional data collected by ABPmer in February 2020 has also been used for the area around Hull and Hull Bend, along with topographic LiDAR data from the Environment Agency (EA) Open Data portal, and MIKE C-MAP.
- 1.2.8 Across the remainder of the model domain, the model bathymetry is defined using other datasets, including from ABP HES, UKHO Marine Data Portal and EMODnet (offshore).
- 1.2.9 All data (where necessary) has been converted to a vertical reference of Mean Sea Level (MSL), using the UKHO VORF.
- 1.2.10 Whilst it is known that the Humber is a dynamic system that can experience significant changes to channels and shoals, the area between Immingham and Grimsby is the deepest and most stable area of the estuary (Ref 1).

Model boundary conditions

- 1.2.11 Tidal boundaries have been applied along all four outer edges of the model, offshore of the Humber (Plate A4). The boundary definitions used in the model are derived from ABPmer’s UK Tide and Surge regional hindcast model (Ref 2).

This regional model, which covers the entire northwest European continental shelf, has been extensively calibrated against available tide gauge and current meter datasets and has been successfully used to provide boundary conditions for a range of high-resolution local models.

1.2.12 For this study, which is focussed on predicting impacts of the Project on typical mean spring and neap tidal conditions, tide-only boundaries (with no meteorological surge component) have been used to drive surface elevations and resultant tidal flows through the Humber Estuary.

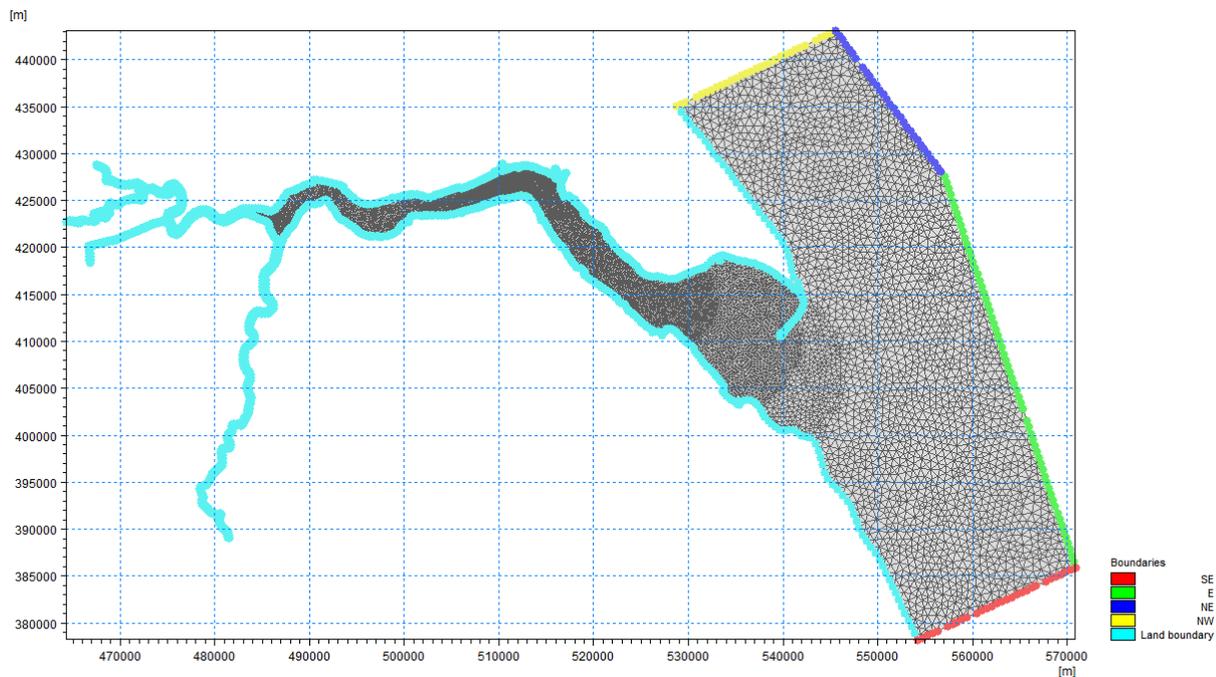


Plate A4. HD model boundaries

Bed roughness

1.2.13 Bed roughness in the model has a large influence on the way in which the water moves through a particular area, affecting both tidal range and phase, as well as the speed and directions of tidal currents. It describes the friction from the seabed ‘felt’ by moving water and is therefore a key variable in the calibration of a model.

1.2.14 The bed roughness map from ABPmer’s existing model of the region was initially adopted for the model and a series of amendments were then made to this, as part of the model calibration process. These amendments were made to help improve the ability of the model to reproduce the measured flow conditions at the site and the wider hydrodynamic regime through the wider estuary.

Calibration and validation data

Water levels

1.2.15 As part of long-term development strategies, Associated British Ports (ABP) commissioned ABPmer to undertake an oceanographic survey surrounding

Immingham Dock. An Acoustic Wave and Current (AWAC) device, combined with Salinity and Turbidity sensors, was deployed on a seabed frame at a location within the Project area. This data, referred to in this report as ‘AWAC’, has been used for the calibration of the associated numerical model. This has been carried out over a mean spring-neap period during the first deployment phase (01/09/22– 16/19/22). In addition to this, UKHO Admiralty predicted water levels at four sites within the estuary were obtained UKHO tide tables. These harmonically derived datasets are referred to as ‘predicted’ or ‘observed’ data in the discussion on model performance.

- 1.2.16 Model validation has been carried out against a second AWAC deployment, also carried out as part of the long-term development strategies, at a subtidal location inshore of the main Oil Terminal, (AWAC 2). Validation has been carried out over a spring-neap tidal period during this second deployment period (26/05/20 – 05/06/20). As well as the data collected at AWAC 2, NTSLF (National Tide and Sea Level Facility) tide gauge data at Immingham and Admiralty predicted tidal levels have also been used for the same period.
- 1.2.17 The model calibration and validation periods were chosen to represent average tidal conditions for the area. Levels have been analysed both visually and statistically following the guidelines outlined in the Model performance metrics and guidelines section below.
- 1.2.18 A summary of the water level data used in the model calibration and validation is provided in Table A1. The locations of the sites are provided in Plate A5.

Table A1. Water level calibration and validation data

Location	Source	Easting	Northing	Duration	Calibration or validation
AWAC	Measured AWAC Data	522355	416011	01/09/22 to 16/09/22	Calibration
AWAC 2	Measured AWAC Data	520750	416397	15/11/19 to 05/06/20	Validation
Spurn Head	Admiralty prediction	540066	411745	01/09/22 to 16/09/22 and 25/05/20 to 13/09/20	Calibration and Validation
Grimsby	Admiralty prediction	528981	411469	01/09/22 to 16/09/22 and 25/05/20 to 13/09/20	Calibration and Validation

Location	Source	Easting	Northing	Duration	Calibration or validation
Immingham	Admiralty prediction	520064	416699	01/09/22 to 16/09/22	Calibration
Immingham	NTSLF Tide Gauge	520064	416699	25/05/20 to 13/09/20	Validation
Hull - King George Dock (KGD)	Admiralty prediction	514808	427683	01/09/22 to 16/09/22 and 25/05/20 to 13/09/20	Calibration and Validation

Current data

- 1.2.19 The predicted flows (speed and direction) at the site were calibrated and validated against measured flow data from the AWAC deployments over the respective deployment periods provided in Table A1.

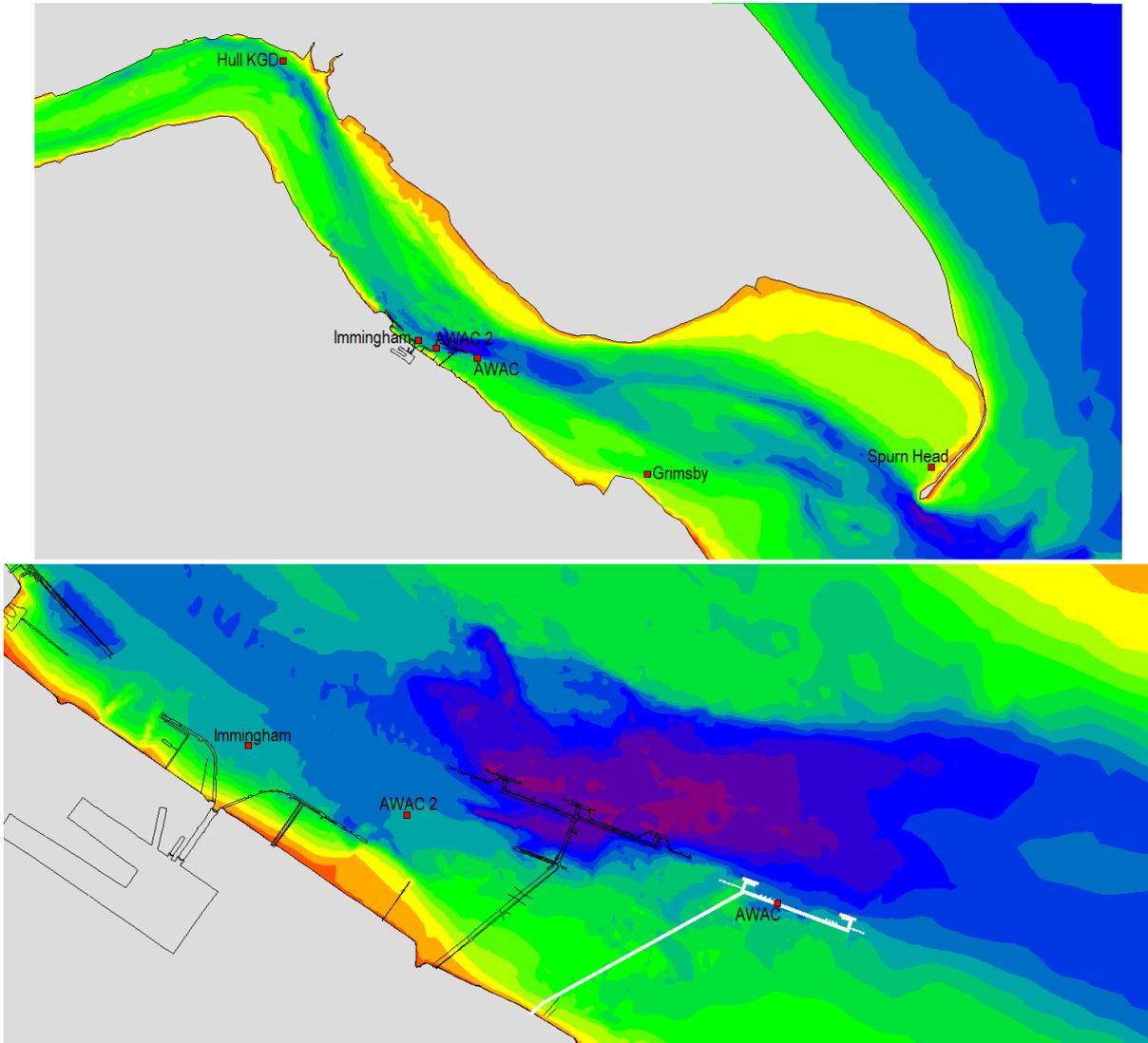


Plate A5. Location of calibration and validation data points (white outline indicates the Project)

Model performance metrics and guidelines

- 1.2.20 The metrics used to assess the hydrodynamic model performance are set out in Table A2. In addition to the target metrics, the model should also simulate any specific features of the tidal shape or flow measurements, such as tidal stands, specific shapes of the flood and ebb profiles and relative flood to ebb flow speed asymmetry. The performance of the model is therefore examined and assessed through a combination of quantitative and qualitative assessments.
- 1.2.21 A level of discrepancy between the observations and model predictions is to be expected and it is considered unnecessary to further justify discrepancies between modelled and measured values that lie within the target metrics. Larger discrepancies may be tolerated in cases where accuracy of the observational data is questionable. If such discrepancies arise, further discussion is required. This discussion should examine the relative importance of the model’s ability to

capture the specific feature identified and how this will affect the modelling results given the intended use of the model.

Table A2. Performance metrics for hydrodynamic models

Metric		Description	Target	Recommended by
Water Levels	Mean surface elevation difference (high and low water level)	Calculated as the mean difference (bias) in water level at high and low water (model minus observed value) for a spring and neap tidal period. The mean difference is also expressed as a percentage of the mean tidal range;	±0.1 m <i>(or to within 10% and 15% of spring and neap tidal ranges respectively)</i> ^{*1}	Ref 4; Ref 5
	Time adjusted fit	This is the phase correction required to yield the minimum difference between the modelled and observed water levels at all timesteps for a spring and neap tidal period and indicates any phase lag in the model;	±15 minutes in coastal areas, ±25 minutes in estuaries	Ref 4
	RMSE surface elevation difference	This value is calculated as the RMS value after the application of the time adjusted fit. Values are calculated over a defined period	0.2 m for A (Design model) 0.25 m for B (Appraisal model)	Ref 7
Flows	Mean flow speed difference (at peak flows)	Calculated as the mean difference between the magnitudes at peak flow, over a defined period. This is also calculated as a percentage value relative to the maximum observed speed;	±0.2 m/s (or 10% to 20%)	Ref 4; Ref 5
	Mean flow direction difference (at peak flows).	Calculated as the mean of the difference in flow direction recorded at times of peak flow, over a defined period;	±10° of measured data	Ref 4;
	Time adjusted fit	This is the phase correction required to yield the minimum RMS differences between the modelled and observed flow	±15 minutes in coastal areas, ±25 minutes in estuaries	Ref 4;

Metric		Description	Target	Recommended by
		speeds at all time-steps over a defined period		
	Flow speed RMSE difference	This value is the RMS of flow speed difference and gives an indication of the agreement between modelled and measured flows throughout the tide and not just at the time of peak flow. This is calculated following the application of the time adjusted fit. Values are calculated over a defined period.	± 0.1 m/s of the peak flow for A (Design model) ± 0.2 m/s of the peak flow for B (Appraisal model)	Ref 7

¹The achievement of absolute levels where the tidal range is significant is likely to be difficult and comparison against tidal range is considered appropriate.

Model calibration

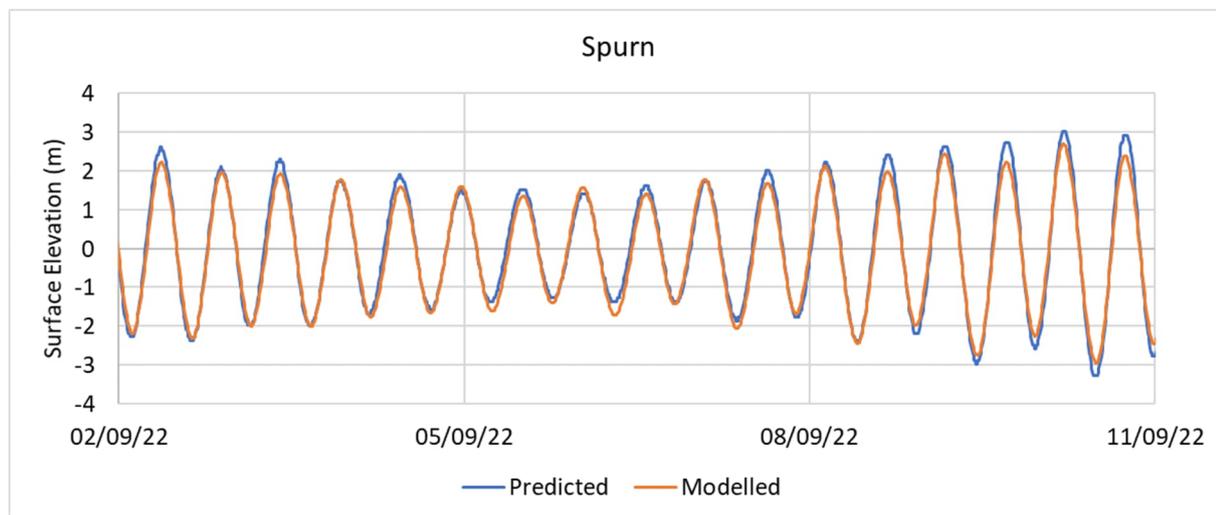
Water Levels

- 1.2.22 The calibrated model has been compared against water levels at the AWAC site and against the UKHO Admiralty tidal predictions for the spring-neap tidal period (02/09/22 – 11/09/22). Levels have been analysed both visually and statistically following the guidelines outlined in the Model performance metrics and guidelines section above.
- 1.2.23 A quantitative statistical analysis of water levels at each of the locations is presented in Table A3, with visual comparisons provided in Plate A6 to Plate A11. The visual comparison shows that the general levels, shape and phasing of the tide is reproduced well. From Spurn Head to Hull, the tidal range increases as the tide propagates up through the estuary and this increase is also reproduced well by the model.
- 1.2.24 A review of the calibration metrics show that the model reproduces the measured water levels well through the estuary, particularly when considering these metrics relative to the tidal range, which is achieved well at all sites.
- 1.2.25 The time-adjusted fit values and RMSE Surface Elevation Difference at all locations are again within the target metrics.

Table A3. Water level calibration statistics

Location (Calibration data source)	High Water Level Difference in m (and as % of Range)	Low Water Level Difference in m (and as % of Range)	Time Adjusted Fit (mins)	RMSE Surface Elevation Difference (m)
<i>Target</i>	<i>± 0.1 m (or to within 10% and 15% of spring and neap tidal ranges)</i>	<i>± 0.1 m (or to within 10% and 15% of spring and neap tidal ranges)</i>	<i>± 15 to 25 minutes</i>	<i>within 0.25 m</i>
AWAC	-0.15 (-3%)	0.15 (3%)	6	0.23
Spurn Head (TT)	-0.22 (-5%)	0.01 (0%)	2	0.23
Grimsby (TT)	-0.20 (-5%)	-0.01 (0%)	-2	0.21
Immingham (TT)	-0.18 (-4%)	0.02 (0%)	-6	0.21
Hull King George Dock (TT)	-0.20 (-4%)	0.11 (2%)	-7	0.23

Note: Where guidance values are exceeded values are shown in **Red**.


Plate A6. Comparison of water levels against Admiralty tidal predictions at Spurn Head

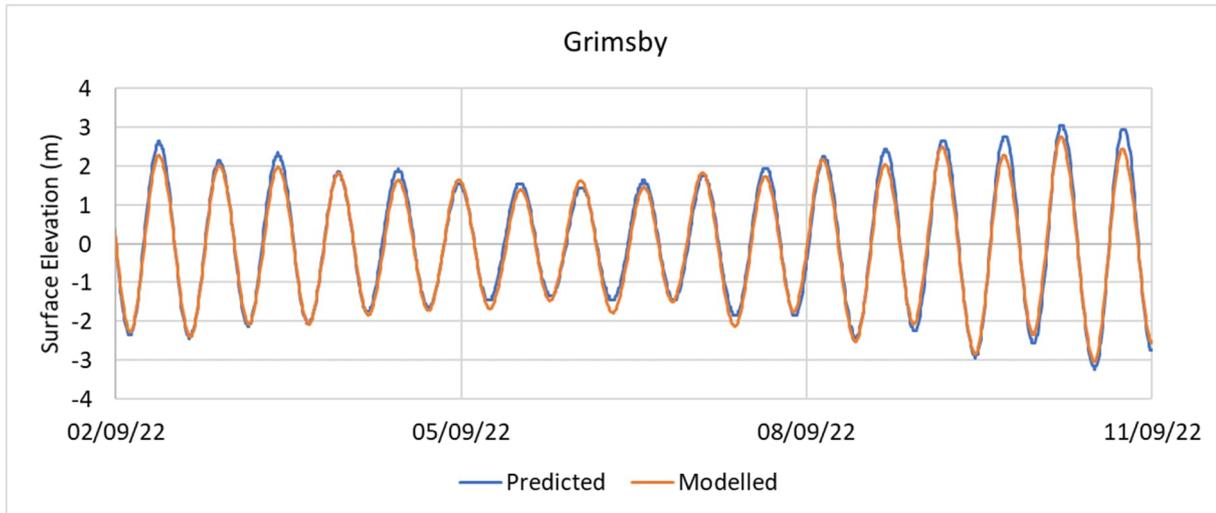


Plate A7. Comparison of water levels against Admiralty tidal predictions at Grimsby

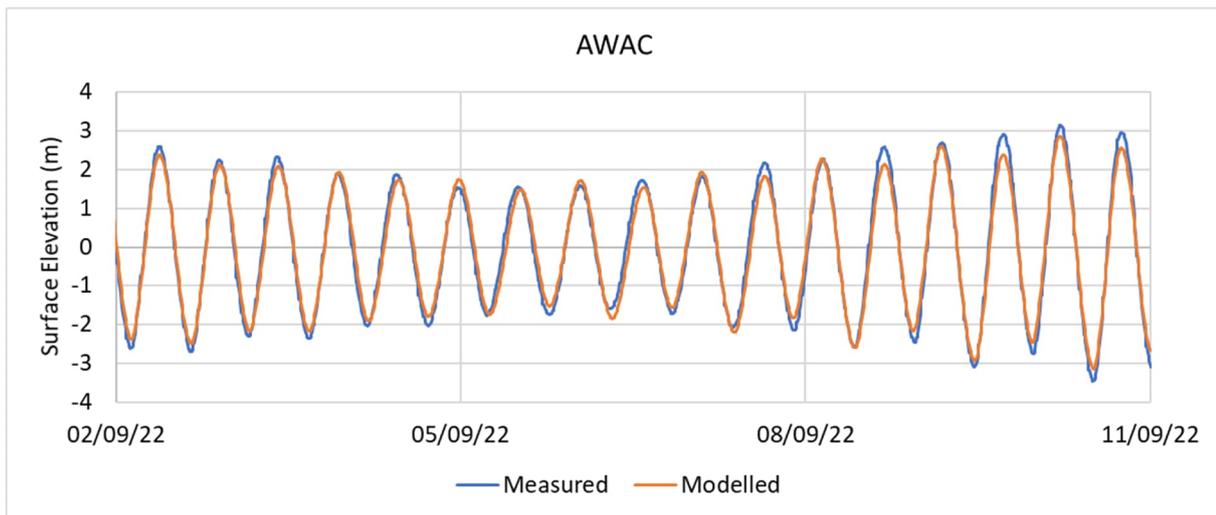


Plate A8. Comparison of water levels at the AWAC deployment location (east of Immingham Oil Terminal)

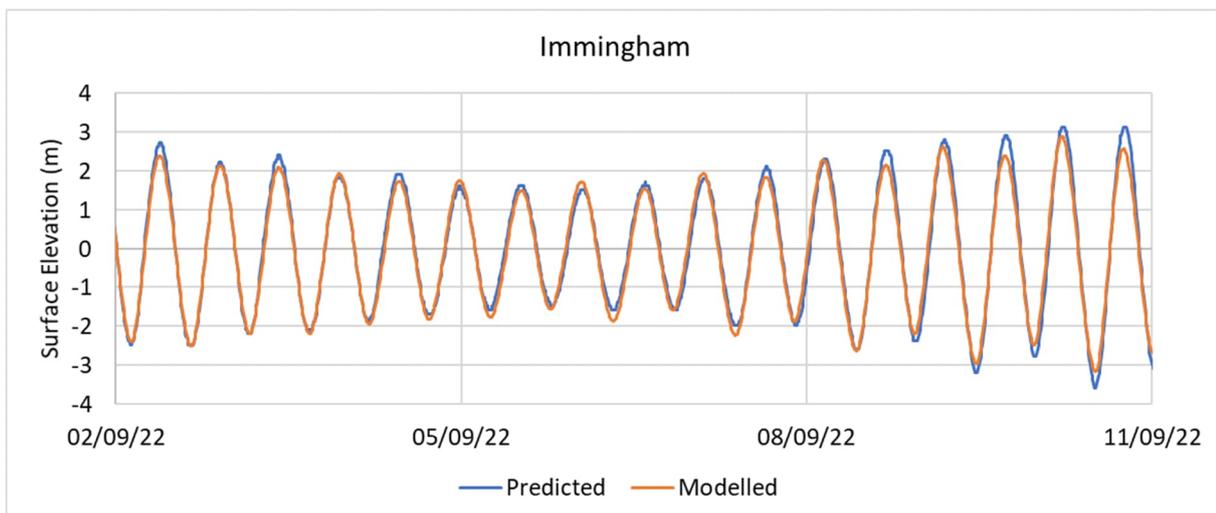


Plate A9. Comparison of water levels at Immingham

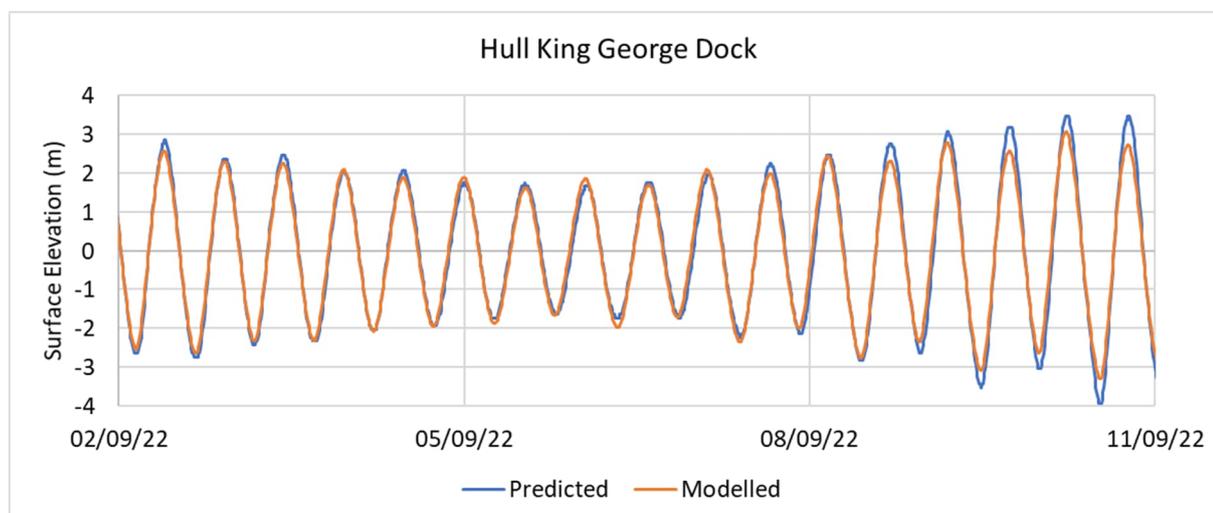


Plate A10. Comparison of water levels against Admiralty tidal predictions at Hull King George Dock

Currents

- 1.2.26 A comparison between the modelled flows and the measured depth-averaged AWAC flow data is provided in Plate A11.
- 1.2.27 The model shows good agreement with the phasing of the flow on both the flood and ebb, and reproduces the ebb dominant flow regime. Ebb flow speeds are reproduced well throughout the spring-neap cycle, although there is a slight overestimation of flow speeds on the neap flood tide. Flow directions on both the flood and ebb are also reproduced well, with both showing a small offset of around 5°. Whilst the AWAC deployment lies in an area where the bed is relatively stable, changes to the local bathymetry do occur, and the small differences observed could be attributed to localised changes between the model bathymetry used in the model and that at the time the measurements were made.
- 1.2.28 A review of the calibration metrics (Table A4) show that the model reproduces the measured flows very well at the AWAC site, with all metrics well within target ranges.

Table A4. Statistics comparing modelled and measured flows during calibration period

Location	Mean Speed Difference (m/s) and (%)		Mean Direction Difference (°)		Time Adjusted Fit (Minutes)	RMS Difference (m/s)
	Peak Flood	Peak Ebb	Peak Flood	Peak Ebb		
Target	±0.2 m/s (or ±20%)		±10°		±25 minutes	0.1 m/s for LEMSA A 0.2 m/s for LEMSA B

Location	Mean Speed Difference (m/s) and (%)		Mean Direction Difference (°)		Time Adjusted Fit (Minutes)	RMS Difference (m/s)
	Peak Flood	Peak Ebb	Peak Flood	Peak Ebb		
AWAC 1	0.08 (5%)	-0.03 (-2%)	6	5	-4	0.2

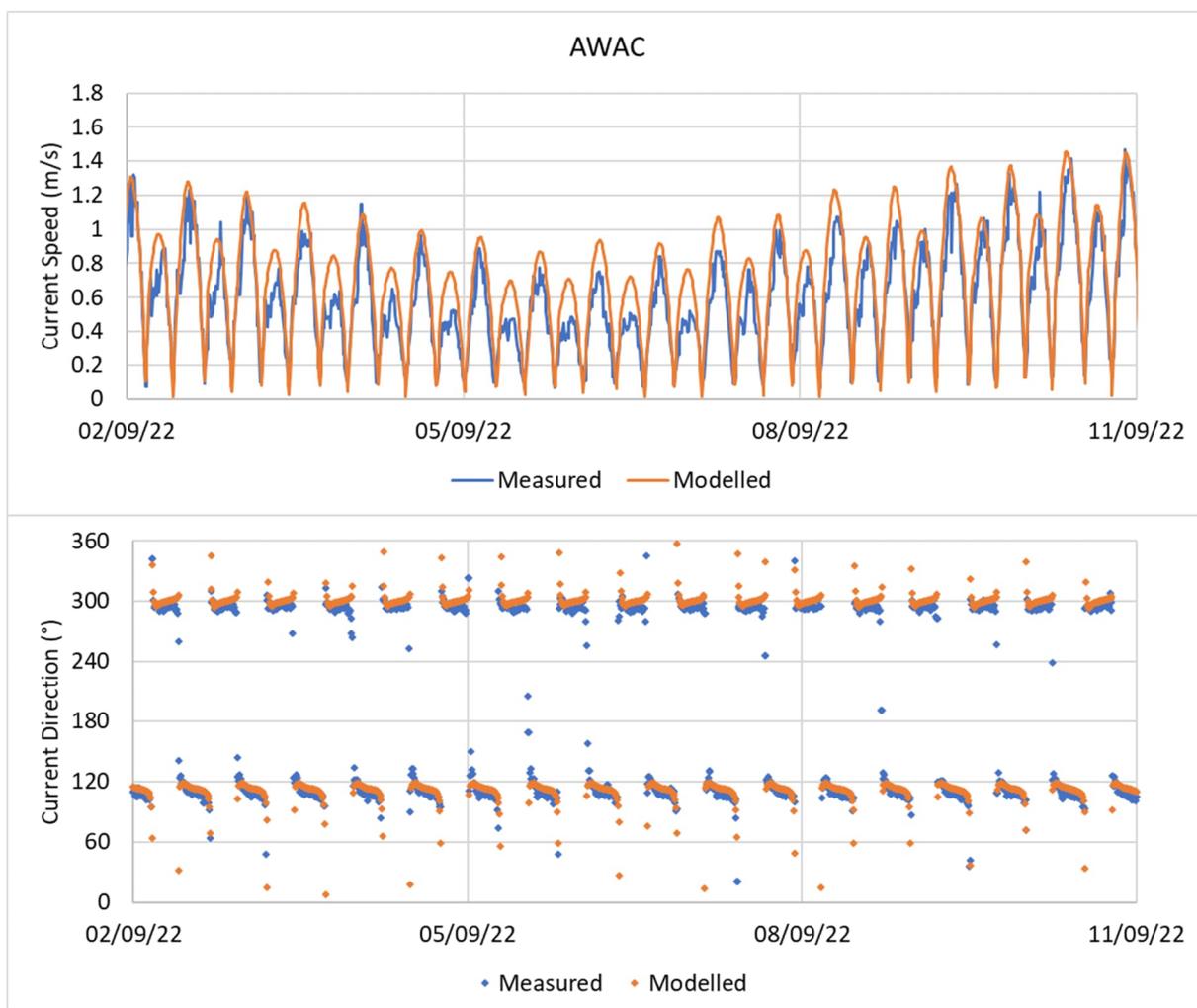


Plate A11. Comparison of flow speed and direction at the AWAC deployment location (East of Immingham Oil Terminal)

Model validation

Water Levels

1.2.29 The model has been validated against water levels at the location of a previous AWAC deployment southwest of the IOT (referred to here as AWAC 2). The validation exercise also uses Immingham NTSLF gauge data and the Admiralty tidal predictions for the spring-neap tidal period (30/08/20 – 09/09/20). Levels

have again been analysed both visually and statistically following the guidelines outlined in the Model performance metrics and guidelines section above.

- 1.2.30 A quantitative statistical analysis of water levels at each of the locations is presented in Table A5, with visual comparisons provided in Plate A12 to Plate A16. The visual comparison shows that the general levels, shape and phasing of the tide is reproduced well. From Plate A12 to Plate A16, the tidal range increases as the tide propagates up through the estuary and this increase is also reproduced well by the model.
- 1.2.31 A review of the validation metrics (Table A5) show that the model reproduces the measured water levels well through the estuary, with all target metrics generally achieved at all sites.

Table A5. Water level validation statistics

Location (Calibration data source)	High Water Level Difference in m (and as % of Range)	Low Water Level Difference in m (and as % of Range)	Time Adjusted Fit (mins)	RMSE Surface Elevation Difference (m)
<i>Target</i>	<i>± 0.1 m (or to within 10% and 15% of spring and neap tidal ranges)</i>	<i>± 0.1 m (or to within 10% and 15% of spring and neap tidal ranges)</i>	<i>± 15 to 25 minutes</i>	<i>within 0.25 m</i>
AWAC 2	0.07 (-2)	0.12 (3%)	12	0.21
Spurn Head (TT)	-0.04 (-1%)	0.20 (5%)	14	0.23
Grimsby (TT)	-0.04 (-1%)	0.20 (4%)	9	0.23
Immingham (NTSLF)	-0.03 (-1%)	0.23 (4%)	2	0.26
Hull Albert Dock (TT)	-0.02 (0%)	0.25 (5%)	5	0.25

Note: Where guidance values are exceeded values are shown in Red.

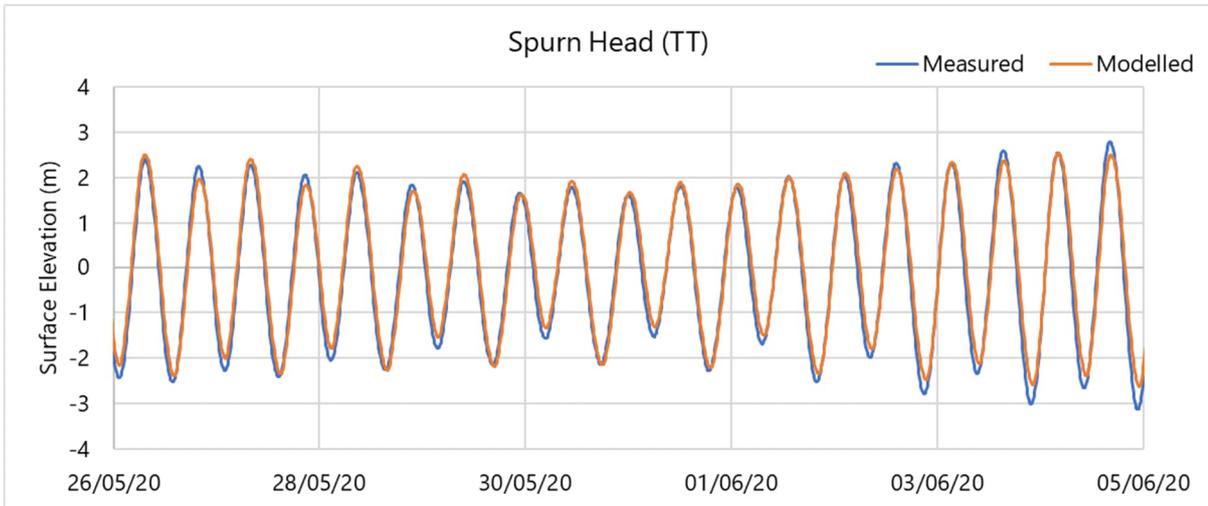


Plate A12. Comparison of water levels against Admiralty tidal predictions at Spurn Head

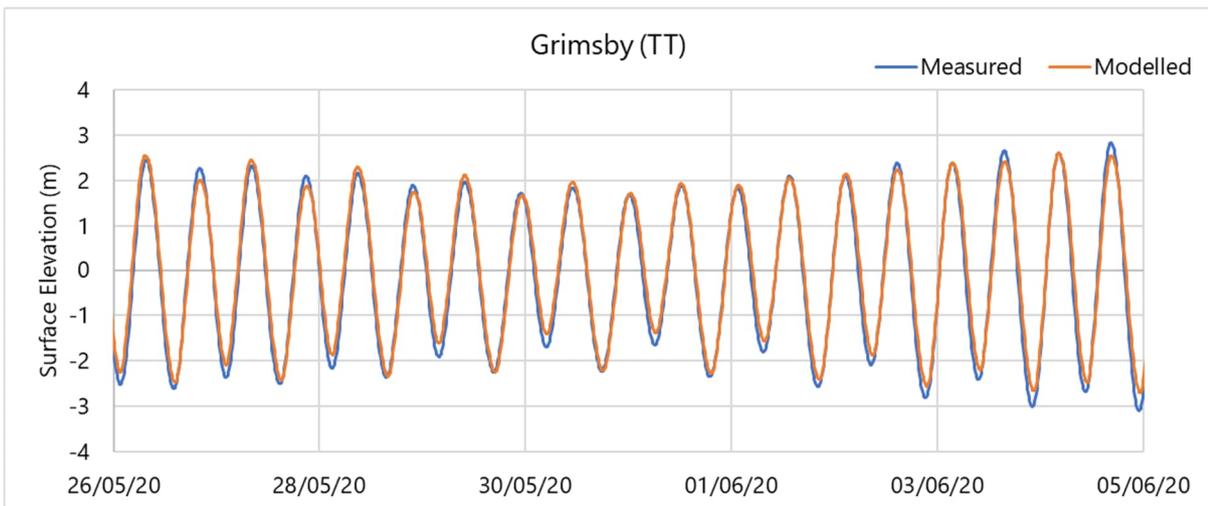


Plate A13. Comparison of water levels against Admiralty tidal predictions at Grimsby

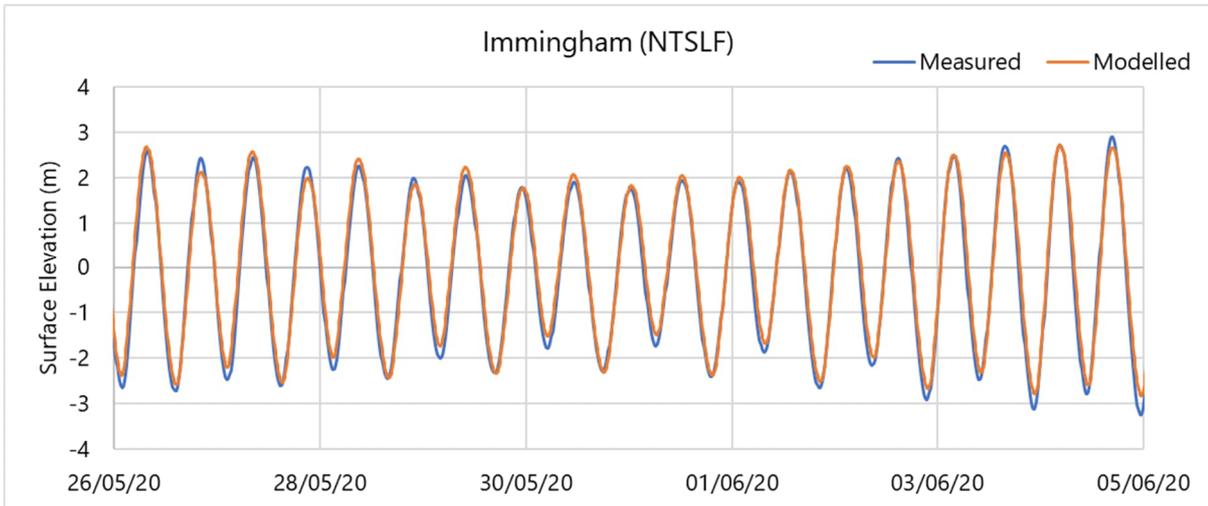


Plate A14. Comparison of water levels against measured NTSLF data at Immingham

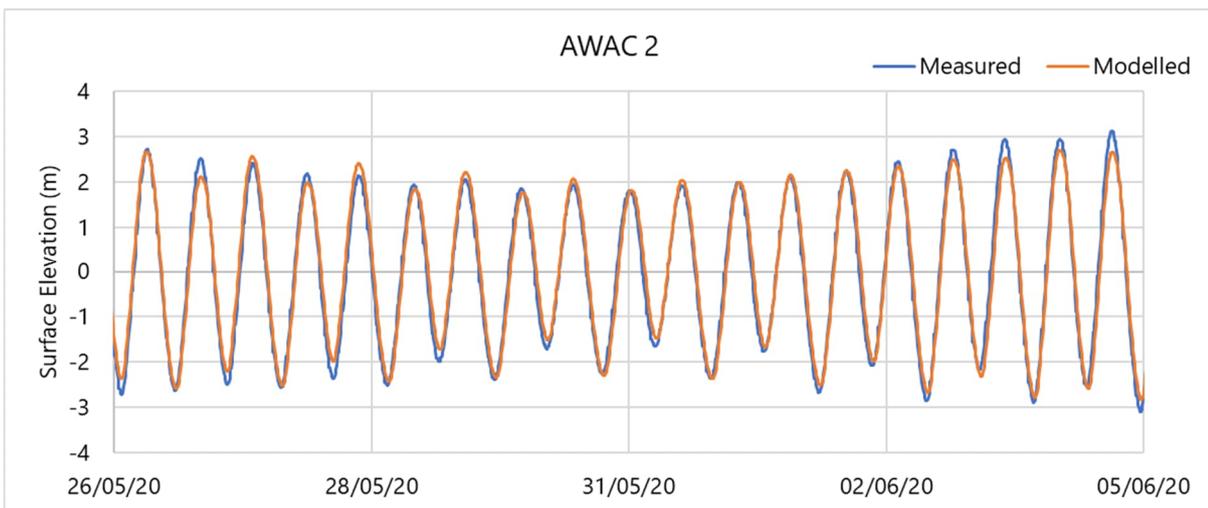


Plate A15. Comparison of water levels at the AWAC 2 deployment location

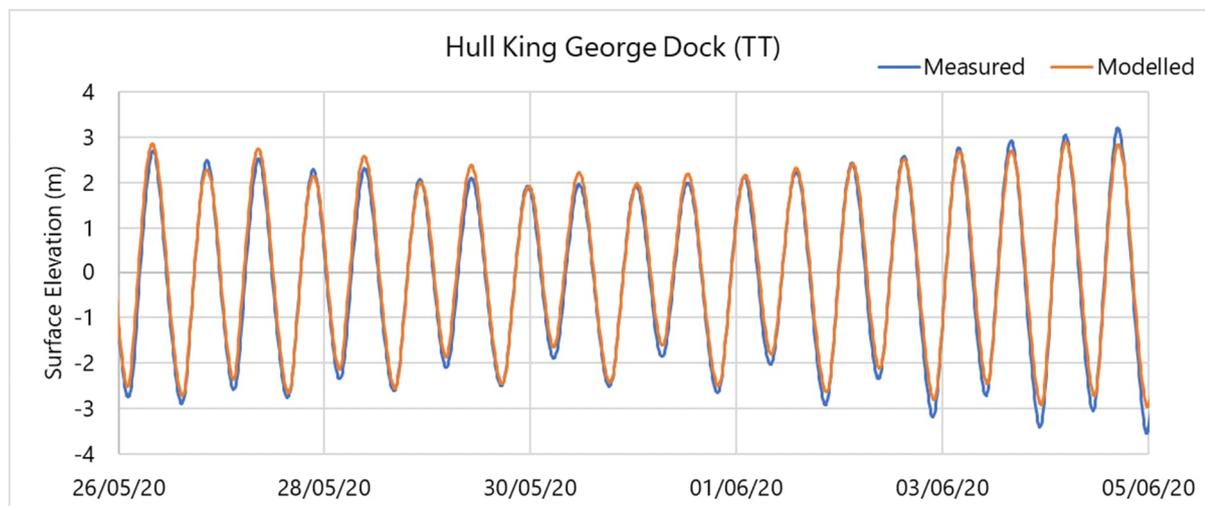


Plate A16. Comparison of water levels against Admiralty tidal predictions at Hull King George Dock

Currents

- 1.2.32 The model again shows good agreement with the phasing and magnitude of the flow on both the flood and ebb (Plate A17). Flow directions are also reproduced well, with no more than 5° difference on either the flood or ebb tides.
- 1.2.33 A review of the validation metrics (Table A6) show that the model is well within target metrics.

Table A6. Statistics comparing modelled and measured flows during validation period

Location	Mean Speed Difference (m/s) and (%)		Mean Direction Difference (°)		Time Adjusted Fit (Minutes)	RMS Difference (m/s)
	Peak Flood	Peak Ebb	Peak Flood	Peak Ebb		
Target	±0.2 m/s (or ±20%)		±10°		±25 minutes	0.1 m/s for LEMSA A 0.2 m/s for LEMSA B
AWAC 2	0.01 (1%)	-0.14 (-8%)	-1	-5	0	0.10

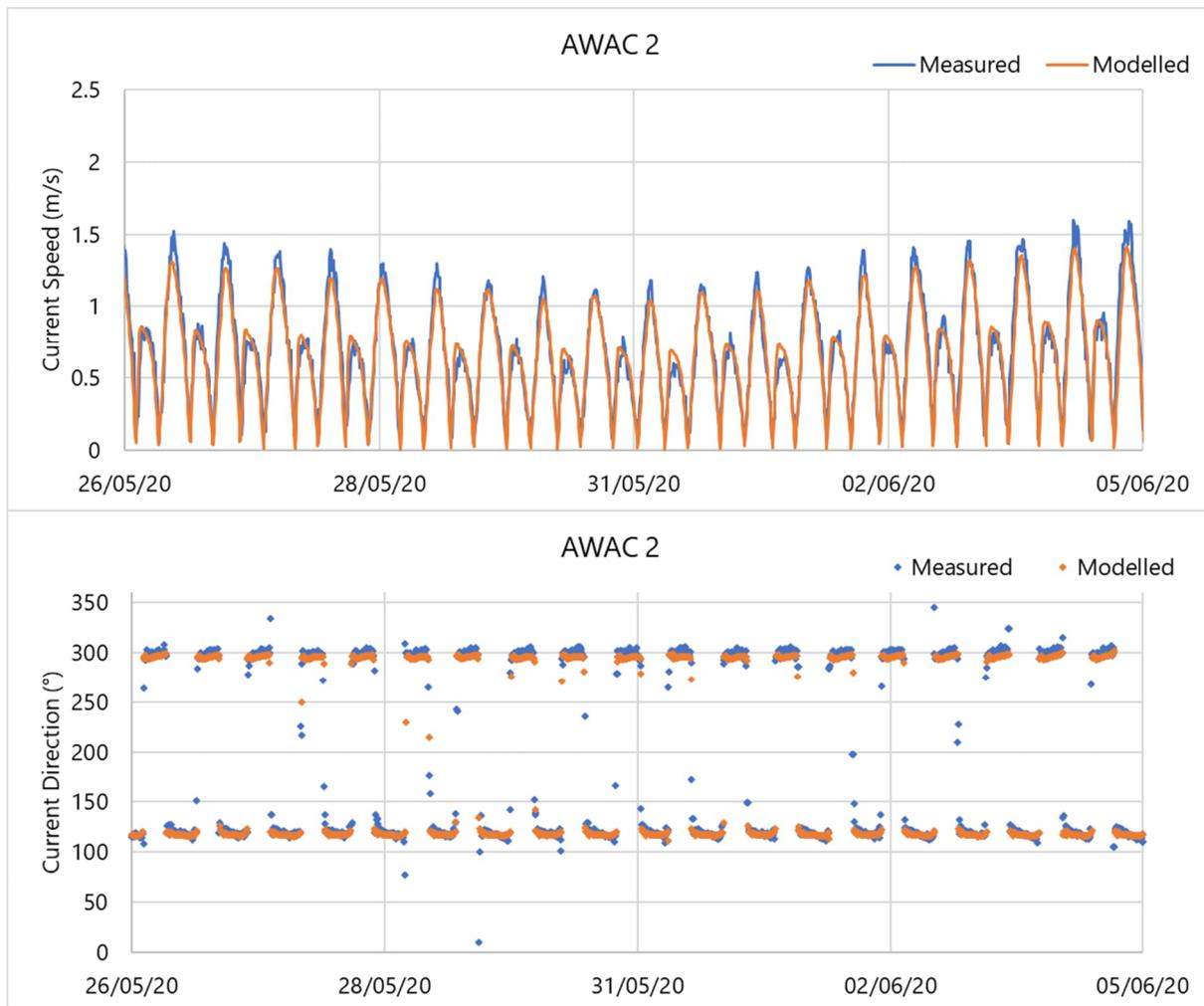


Plate A17. Comparison of flow speed and direction at the AWAC 2 deployment location

1.3 Summary of hydrodynamic model performance

1.3.1 The numerical hydrodynamic model has been set up, calibrated and validated as described above. Water levels throughout the Humber Estuary are replicated well within the model, particularly when comparing against the target metrics for HW and LW bias and the associated time-adjusted fit. Comparisons against the measured flows show the model is also good at representing the peak magnitudes and flow directions in the vicinity of the study area. The shape of the tidal wave as it propagates up through the estuary is also well represented in the model.

1.3.2 Overall, the model is considered to be performing well and is able to replicate the hydrodynamic regime across the study area with sufficient precision. The hydrodynamic modelling is considered suitable for use in assessing the predicted impact of the Project on water levels and flows within the Humber Estuary. The hydrodynamic model is also considered to provide an appropriate basis to examine the sediment transport regime within the estuary and to examine the

dispersion of material released from the associated dredging operations (Section 1.4).

Sediment Transport Model

1.3.3 The study also aims to assess the potential impact on sediment transport processes, as a result of the proposed Project. This assessment is built around existing knowledge of the Humber system and informed by bespoke numerical modelling of the baseline and scheme scenarios. To achieve this, the DHI Mud Transport (MT) module has been applied, driven by the outputs from the hydrodynamic modelling described above. The following sections describe the set up and verification of this transport module.

Mud transport (MT) module setup

1.3.4 The MT module is driven by the outputs from the HD modelling; as such, the model extent, mesh, bathymetry, bed roughness and HD boundary conditions are as described in the previous sections.

Sediment parameters

1.3.5 Grab sampling data from the project survey campaign has been analysed for particle size distribution (Table A7 and Plate A18), and the average composition of the bed material across the proposed Project area (primarily sandy Mud) has defined the sediment grading used within the MT model.

Table A7. Particle size distribution across the site

Sample	Percentage composition (%)			Sediment description*	Mean grain size (d50) (µm)
	Mud	Sand	Gravel		
1	96.69	3.31	0.0	Mud	7.8
2	94.11	5.89	0.0	Mud	8.2
3	96.32	3.68	0.0	Mud	7.0
4	71.10	28.90	0.0	Sandy Mud	20.1
5	57.35	42.65	0.0	Sandy Mud	27.7
6	63.76	36.24	0.0	Sandy Mud	23.6
7	71.51	28.49	0.0	Sandy Mud	17.9
8	55.43	44.57	0.0	Sandy Mud	30.6
HU56_01	0.0	100.0	0.0	Sand	159.0
HU56_02	1.6	84.0	14.4	Slightly Gravelly Muddy Sand	186.1

Sample	Percentage composition (%)			Sediment description*	Mean grain size (d50) (µm)
	Mud	Sand	Gravel		
HU56_03	37.1	16.2	46.6	Muddy Gravel	83.8
HU56_04	16.3	12.1	71.5	Gravelly Mud	17.7
HU56_05	18.7	80.1	1.2	Gravelly Sand	707.9
HU56_06	35.0	17.0	48.0	Muddy Gravel	73.7
HU60_01	0.0	100.0	0.0	Sand	230.7
HU60_02	0.0	100.0	0.0	Sand	227.7
HU60_03	0.4	61.7	37.9	Slightly Gravelly Muddy Sand	148.1
HU60_04	0.0	100.0	0.0	Sand	232.7
HU60_05	0.0	100.0	0.0	Sand	202.1
HU60_06	0.0	100.0	0.0	Sand	223.6
* Sediment description after <i>Ref 8</i>					

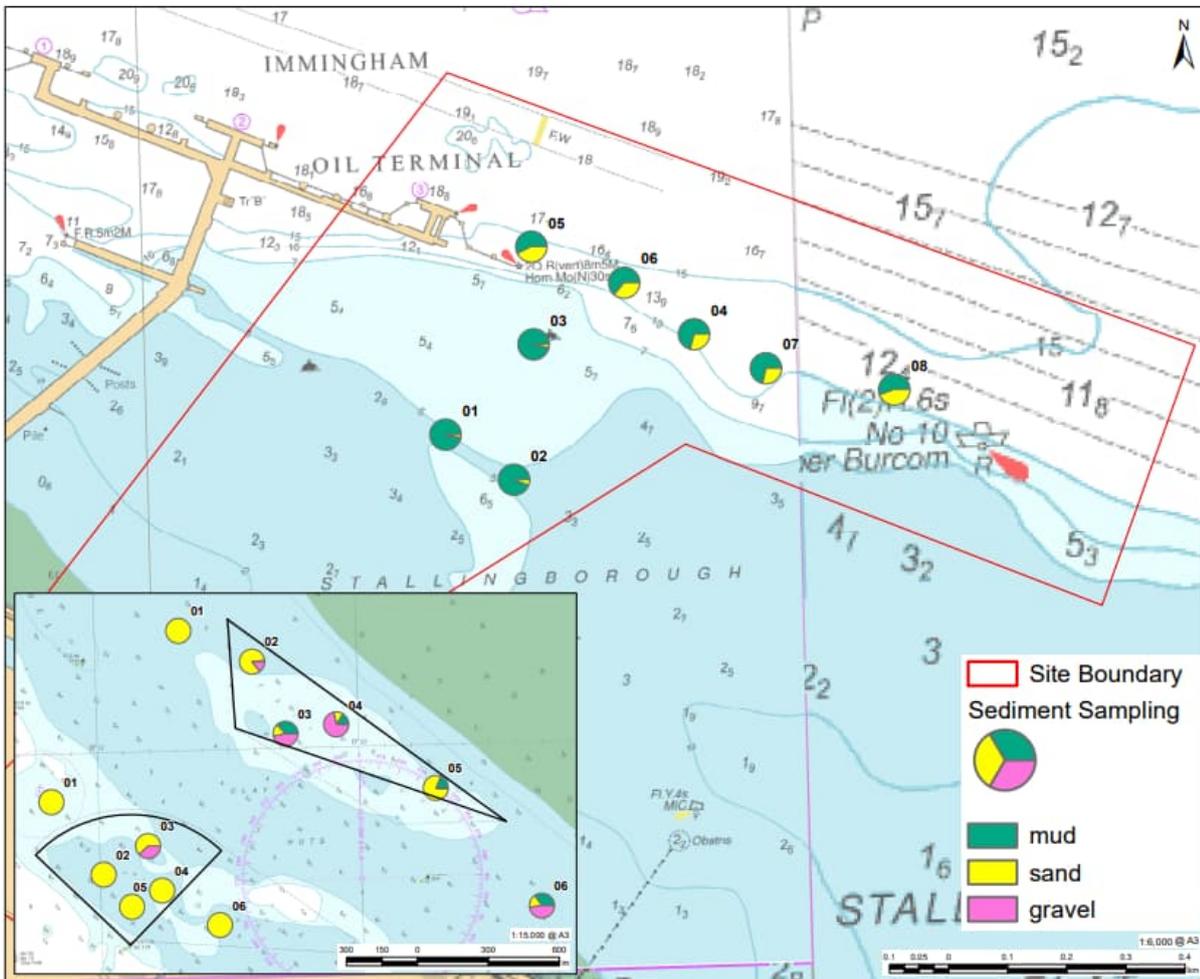


Plate A18. Particle size distribution across development site

1.3.6 Table A8 shows the range of model setup parameters (calculated using industry-standard formulae; for example, from van Rijn (Ref 9)), which have been adjusted through the model verification exercise (see following section).

Table A8. Mud Transport module - Sediment input parameters

Input parameter	Description
Settling parameters (mg/l):	
Concentration for flocculation	500
Concentration for hindered settling	1,600
Critical shear stress for deposition (N/m ²)	0.10
Critical shear stress for erosion (N/m ²):	
Layer 1	0.53
Layer 2	0.90

Input parameter	Description
Initial SSC (mg/l)	100
Initial bed thickness (m): Layer 1 Layer 2	Variable (see Plate A19) 0.10
Boundary inputs (mg/l)	20

1.3.7 The model bed is comprised of two defined layers: a ‘soft’ layer that material initially settles to, which is relatively low density and more easily re-eroded; and a ‘harder’ lower layer that defines a more consolidated bed. The lower layer is initially defined by a constant thickness of 0.1 m, whilst the upper layer uses a spatially varying thickness, based on regional sediment distribution across the study area. This varying thickness map is shown in Plate A19.

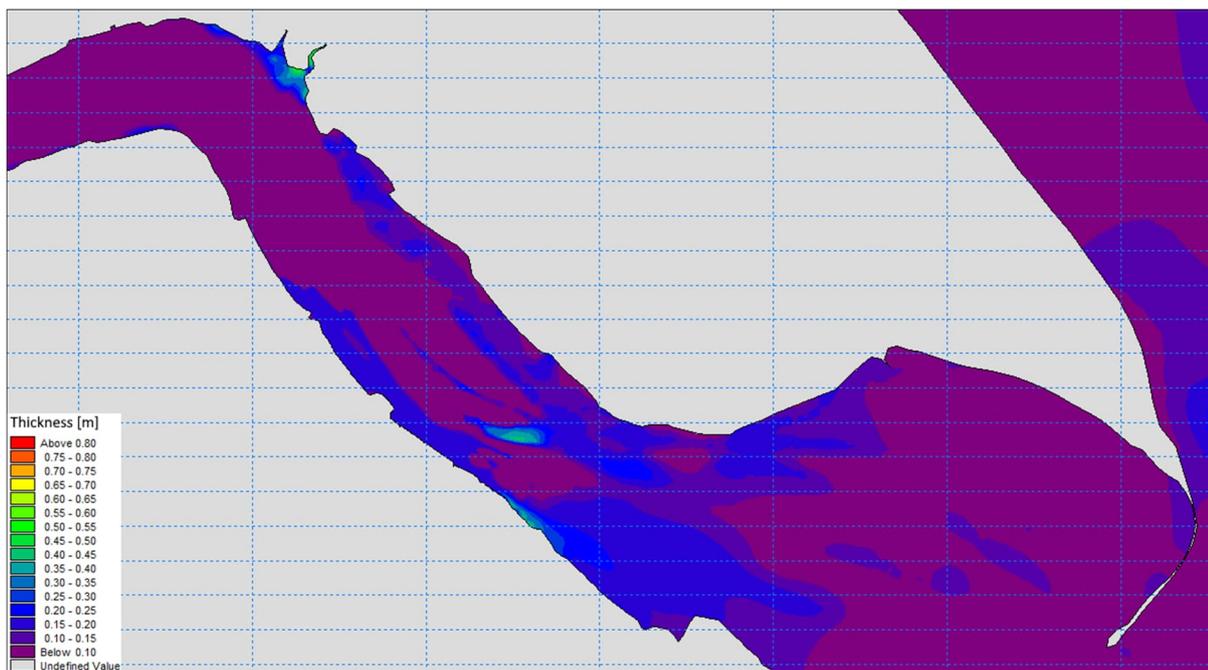


Plate A19. Spatially varying thickness map for the initial upper bed layer

Verification data

1.3.8 Dredge load information for the existing local Immingham berths and dock entrances has been assessed, alongside previous studies on historic bed level change (e.g. ABP R&C 1995), to consider the typical accretion rates in known parts of the local study area. Data for these areas covers the period from 2004 to 2020, which have subsequently been used to ‘train’ the baseline MT model run to provide representative levels of bed thickness change. In this way, whilst a ‘formal’ calibration process (in the same way as described above for the hydrodynamic model) is typically not undertaken with sediment transport

modelling, the model can be considered to be ‘verified’ against real-world data. Table A9 shows the typical accretion rates from the available baseline data.

Table A9. Typical accretion rates in the vicinity of the study area

Location	Accretion Rate (m/yr)*		
	Minimum	Maximum	Average
Immingham Outer Harbour (IOH)	3.5	11.9	7.2
West Jetty Extension	0.1	2.8	0.5
Immingham Gas Terminal (IGT)	0.6	3.5	1.0
Immingham Bellmouth	1.4	3.5	2.3
Humber International Terminal (HIT)	1.8	7.2	3.7

* accretion rates defined by reported dredge load information and based on an assumed bed density of 1,300 kg/m³

1.3.9 In addition to the accretion rates, modelled timeseries of suspended sediment concentration (SSC) have been compared against measurements from the project survey deployment. This process provides a further measure of model performance, allowing for consideration of suspended (as well as bedload) transport processes. The measured SSC data shows evidence of some peak concentrations that are likely a result of the deployment setup. Hence, the comparison of the modelled values focusses on the general trend (in measured data) across a mean spring neap tidal cycle.

Model performance

- 1.3.10 The MT module has been set up as described above, and a range of input parameters adjusted in order to achieve a suitable representation of the baseline accretion rate in the dock entrances in the vicinity of the proposed scheme.
- 1.3.11 A key consideration in determining the depth of any bed accretion is the *in-situ* density of the deposited material. Bed densities can be expected to vary from site to site and, hence, the thickness of any accretion will vary also (for a given mass of sediment). A lower density will result in a greater volume, hence a thicker accretion. In contrast, a higher density will contain the sediment mass in a smaller volume, hence bed thickness will be lower.
- 1.3.12 Plate A20 shows the modelled baseline accretion across a mean spring neap cycle. This shows the general siltation across the existing dredged berths (which are included in the model baseline as dredged berth pockets, represented by the recent bathymetric survey datasets), including HIT, IOH, east and west jetties and Immingham Bellmouth. Within the proposed IGET Project area, the baseline model indicates a generally stable bed with little or no siltation.

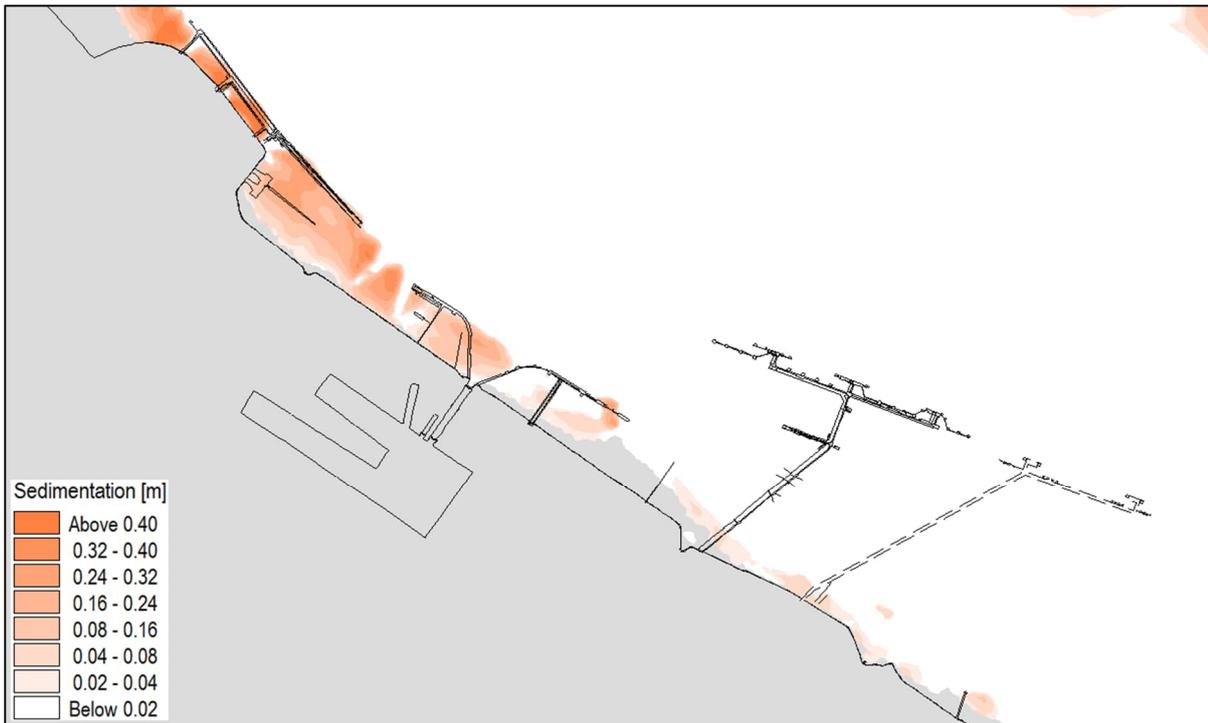


Plate A20. Baseline sedimentation over a mean spring neap cycle

1.3.13 Analysing the outputs from the baseline spring neap modelled period (Plate A20) and applying a linear scaling factor to cover an annual period, Table A10 shows the modelled accretion rates in the dock entrances, for an *in-situ* bed density of 1,300 kg/m³. This table also compares the modelled rates against those calculated from the range of dredged volumes provided in the verification data (and as summarised in Table A9).

Table A10. Comparison of modelled accretion rates along Immingham frontage

Location	Comparison of Accretion Rate (m/yr)	
	Average rate from dredge load data	Modelled rate from MT module
Immingham Outer Harbour (IOH)	7.2	3.9
West Jetty Extension	0.5	0.5
Immingham Gas Terminal (IGT)	1.0	0.8
Immingham Bellmouth	2.3	1.8
Humber International Terminal (HIT)	3.7	2.6

- 1.3.14 The rates from the model compare very well with those defined from the dredging records and analysis of recent bed level change (Table A9). The majority of locations are very close to the average value derived from the dredge load data, whilst the modelled rate at all locations is within the minimum/maximum envelope exhibited by the data provided in Table A9. Small variations to assumed bed density will also influence these predicted accretion rates. Moreover, the general pattern of relative accretion rates in the dredge load data is matched by the model, with IOH showing the largest predicted accretion and the West Jetty Extension the smallest.
- 1.3.15 Alongside comparison of the modelled deposition values against the dredge load data, predicted SSC values have also been compared against measured values from the earlier survey deployment at the close to the proposed development site (Ref 3). This shows that the model is in generally good agreement with the overall trend across the mean spring neap tidal cycle. The variance in peak values between spring and neap tides is well replicated by the model, as are the general peak concentrations, which coincide with the times of peak ebb and flood flows.

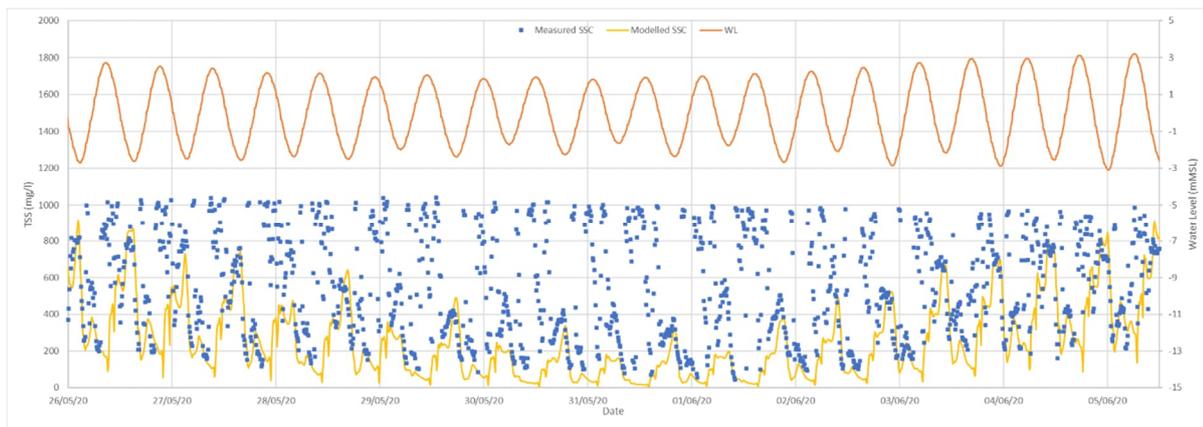


Plate A21. Comparison of modelled and measured SSC

- 1.3.16 Overall, the MT model is performing well, and is considered suitable for use in investigating the potential impacts on mud transport as a result of the proposed scheme.
- 1.4 Dredging Operations Dispersion Model
- 1.4.1 The potential fate of dredge arisings and spoil from removal to licensed disposal sites has been assessed using the DHI MIKE Particle Tracking (PT) module, driven by outputs from the hydrodynamic model (as described above). The model setup has been informed through the verification of the accompanying mud transport module (see above), with the subsequent assessment using the dredge volumes from the project engineers, an understanding of the likely dredging processes and of the availability of open, suitable disposal sites.

Particle Tracking (PT) module setup

- 1.4.2 As with the MT module (above), the PT module has also been run using the outputs of the calibrated hydrodynamic model (Section 1.2) to drive the plume dispersion assessment. The composition of the dredged material (and that of the subsequent disposal) has been informed by the sediment sample analysis, carried out for the project. Table A11 provides the derived composition information used in the plume dispersal modelling.
- 1.4.3 A range of scenarios have been developed and examined, which have simulated a range of dredge and disposal operations over a number of tidal conditions (spring, neap, flood, ebb). Details of the scenarios examined are provided within the Physical Processes PIER Chapter.

Table A11. Plume dispersion module - Sediment properties

Sediment description	Grain diameter (μm)	Settling velocity (m/s)	Percentage bed composition (%)
Fine sand	100	6×10^{-3}	21
Coarse silt	22	3×10^{-4}	57
Fine silt	4	1×10^{-5}	22

Model performance

- 1.4.4 No formal verification of the PT model has been undertaken, but provisional test runs were carried out and the results examined to ensure that the numerical modelling tool is behaving as expected.

1.5 Wave Model

- 1.5.1 In order to assess the impact of the Project on the wave conditions adjacent to the site, a DHI MIKE21 SW (spectral wave) model has been constructed. The model has subsequently been used to examine how waves conditions will be affected during extreme and more frequently occurring events.
- 1.5.2 The model setup (and validation) is described in the following sections.

Model Grid

- 1.5.3 The wave model uses the same model grid and bathymetric data as described in Section 1.2 for the hydrodynamic module.

Model parameters

- 1.5.4 The primary model parameters are as described below, with the model boundary and forcing conditions described in subsequent sections.
- a. Spectral resolution: The model was run with 22 frequencies, covering wave periods from approx. 0.5 to 15 seconds.

- b. Model Bed friction: The model uses a Nikuradse roughness value of 0.001 m constant over the model domain. This value is significantly lower than the default value of 0.04 m, but from experience is considered to be much more appropriate given the nature of the site.
- c. Wave breaking: Included using default parameters.
- d. Wave - Wave interaction: Included using quadruplet-wave interaction.
- e. Currents: The effect of currents is excluded from the main simulations and is of limited importance at high water when waves at the site will be greatest, although the sensitivity to currents was examined through the verification exercise.
- f. Diffraction: Tested and subsequently excluded from model setup as found to be of limited importance over study area.

Wave model verification

- 1.5.5 The principle aim of the present assessment is to examine how waves within the Humber and adjacent to the site may be affected by the development, which is to be assessed by examining wave conditions at the site for a number of discrete extreme and more frequent events. Therefore, a more formal calibration/validation exercise has not been undertaken, instead the general performance of the model has been examined by simulating wave conditions at the site, over a short period during which waves were recorded at the site during the AWAC 2 deployment. The location of the AWAC 2 deployment is shown in Plate A5.
- 1.5.6 The period used in this verification exercise covers the 25/05/20 to 05/06/20, during which a number of events were recorded by the Nordic AWAC. For this period, offshore wave conditions were extracted from the ABPmer SEASTATES hindcast wave model of the UK continental shelf. Wave conditions were extracted along the full length of the boundary.
- 1.5.7 The model was then run with varying waters levels extracted from a hydrodynamic model simulation for the same period (Section 1.2), both with and without currents included. Associated wind speeds from the National Centers for Environmental Prediction (NCEP) Climate Forecast System v2 (CFSv2) (<http://rda.ucar.edu/datasets/ds094.1/>) hindcast database were also applied to the model.
- 1.5.8 The results of this verification simulation (with currents included) are presented in Plate A22. The model provides a good comparison against the measured data. Sensitivity testing has showed that applying variations to water levels and currents in the model has no notable effect on model performance. Discrepancies in the comparison of the wave events evident in the measured data between the 28 and 31 May 2020, are likely a result of other factors that are influencing wave height, such as thermal winds (particularly given the record levels of sunshine experienced over the UK during May 2020), which are not represented in the model.
- 1.5.9 Overall, the performance of the model is considered sufficient for use in the subsequent assessment of potential impact on defined wave events.

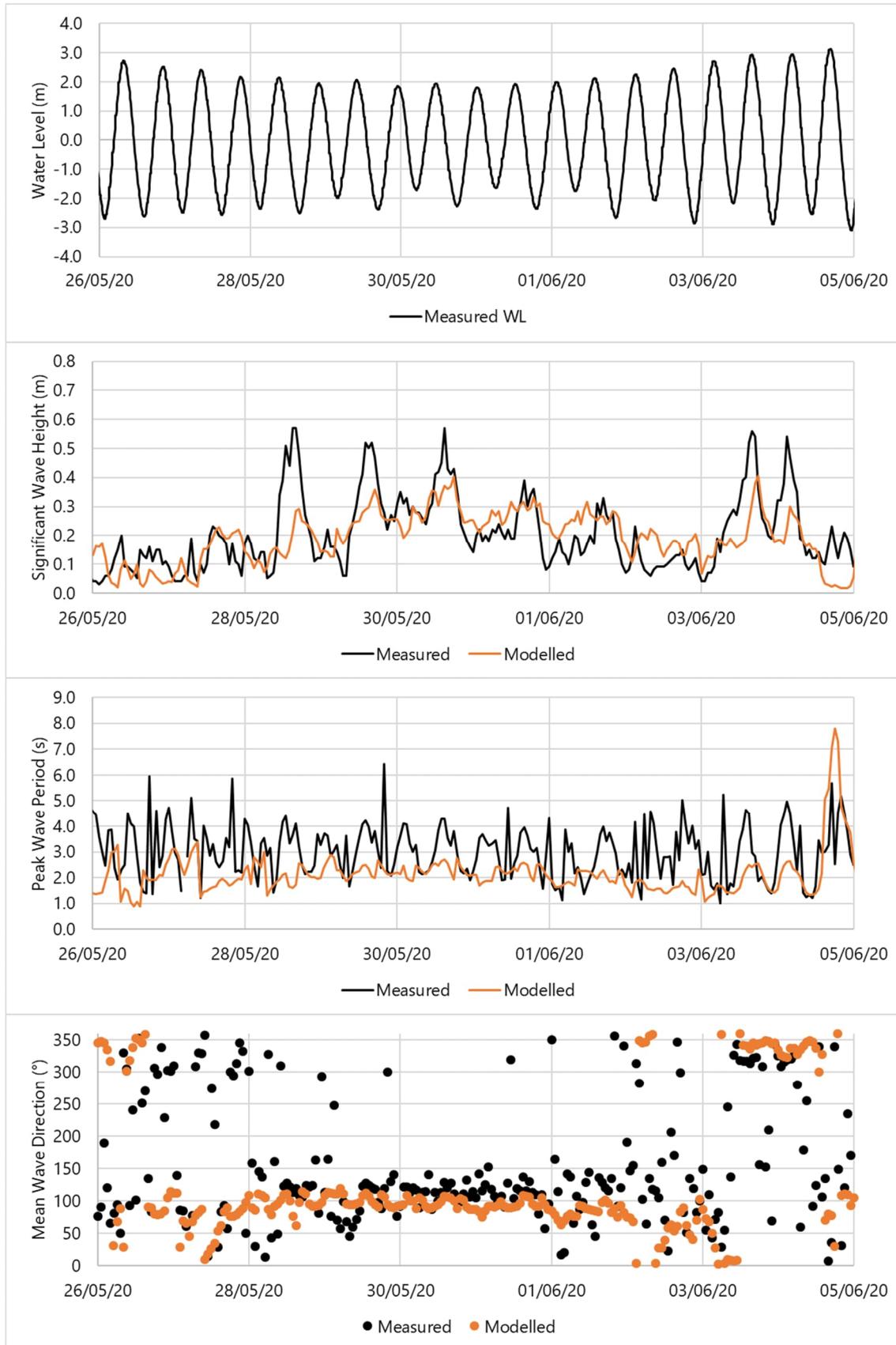


Plate A22. Comparison of H_s , T_p and mean wave direction at the Nordic AWAC deployment location (Immingham Oil Terminal).

Derivation of wave conditions used in impact assessment

- 1.5.10 Within the main assessment, the effect of the Project on wave conditions in the Humber and adjacent to the site has been examined for a number of discrete extreme and more frequently occurring events. The derivation of these discrete events is described below.
- 1.5.11 Long-term hindcast wave data at the model boundary (just offshore of the entrance to the Humber Estuary) have been extracted from the ABPmer SEASTATES hindcast wave model of the UK continental shelf (www.seastates.net). The water depth at the data extraction point is approx. - 15 mODN.
- 1.5.12 This SEASTATES hindcast model has been extensively calibrated at locations around the UK coastline and provides a 41-year hourly hindcast of wave parameters (including height, period and direction), covering the periods 1979 and 2020, inclusive.
- 1.5.13 The extracted data is presented in Plate A23 and Table A12 as both a wave rose and scatter table of significant wave height vs mean wave direction.
- 1.5.14 From this data, three directional sectors have been selected from which to derive extreme wave conditions entering the Humber, based on the largest fetch lengths at the site. These are shown in Table A13 and highlighted in Table A12 with coloured shading in the table headers.
- 1.5.15 A 'central' direction has also been selected for each sector, which will be the direction from which the extreme waves are specified in the model simulations. For the eastern and south eastern sectors this sits in the true centre of the filtered directional bins. For the north east sector, the larger wave events prevail from more northerly sectors, however, the extreme waves derived from the NE sector have been modelled from a direction of 45° as these directions will have greater potential for propagating into the estuary. In this way, the modelling approach represents a conservative worst case.
- 1.5.16 In order to associate a wind condition with each wave event, wind data has also been extracted from the ABPmer SEASTATES model for the same location. These winds are sourced from the National Centers for Environmental Prediction (NCEP) Reanalysis II dataset between 1979 and 2009 and, more recently (2010 to present), from the Climate Forecast System v2 (CFSv2) (<http://rda.ucar.edu/datasets/ds094.1/>) hindcast database. These are the wind fields used to drive the SEASTATES wave hindcast. The wind speed parameters are considered representative of speeds at 10 m above sea level with a 1-hourly averaging period.

Table A12. Significant wave height vs. mean wave direction at the Humber boundary location

		Mean Wave Direction ('from)																			Sum						
		NE				E			SE			157.5 - 172.5	172.5 - 187.5	187.5 - 202.5	202.5 - 217.5	217.5 - 232.5	232.5 - 247.5	247.5 - 262.5	262.5 - 277.5	277.5 - 292.5		292.5 - 307.5	307.5 - 322.5	322.5 - 337.5	337.5 - 352.5		
		352.5 - 7.5	7.5 - 22.5	22.5 - 37.5	37.5 - 52.5	52.5 - 67.5	67.5 - 82.5	82.5 - 97.5	97.5 - 112.5	112.5 - 127.5	127.5 - 142.5	142.5 - 157.5	157.5 - 172.5	172.5 - 187.5	187.5 - 202.5	202.5 - 217.5	217.5 - 232.5	232.5 - 247.5	247.5 - 262.5	262.5 - 277.5	277.5 - 292.5	292.5 - 307.5	307.5 - 322.5	322.5 - 337.5	337.5 - 352.5	Sum	
Hs (m)	6.5 - 7																									0	
	6 - 6.5																										0
	5.5 - 6																									2	
	5 - 5.5	6	3	3																	2	1					15
	4.5 - 5	18	44	16	4	1					1	2						5									110
	4 - 4.5	63	88	36	63	16				1	4	2	4	9	7	2	2	4	4	8	8	15	12	7	4	23	382
	3.5 - 4	333	246	67	70	62	38	11	12		3	10	24	17	1	11	15	10	20	15	33	30	20	30	43	1121	
	3 - 3.5	860	368	137	109	168	178	62	46	18	16	45	60	80	36	29	37	25	44	63	93	140	71	58	134	2877	
	2.5 - 3	1887	653	348	285	362	415	212	84	87	117	132	237	281	233	170	103	126	134	194	289	384	268	196	342	7539	
	2 - 2.5	3066	1191	609	634	610	729	468	318	374	256	349	638	850	1031	694	439	494	556	588	816	834	568	498	1109	17719	
	1.5 - 2	6071	3057	1372	1453	1379	1217	1340	1086	1076	895	978	1443	2158	2862	2619	1939	1609	1575	1752	1722	1569	1318	1489	2920	44899	
	1 - 1.5	11374	9863	4587	3851	3597	3386	3098	3052	2941	2718	2478	3320	4441	5462	5426	4487	3491	3455	3394	3607	3405	3271	3791	5129	103624	
	0.5 - 1	10262	12359	8638	7655	6574	6723	6578	5629	5807	5372	4838	5405	6918	7296	7006	6380	5284	5169	4995	5093	4750	5314	6002	7769	157766	
	0 - 0.5	1242	849	752	780	926	862	1047	1139	1069	1033	953	955	1002	1174	1195	1166	1134	1049	882	819	816	737	760	1005	23346	
Sum	35182	28671	16565	14904	13695	13548	12816	11367	11376	10413	9789	12091	15754	18097	17152	14570	12182	12010	11899	12493	11942	11575	12831	18478	359400		
Percentage	9.8%	8.0%	4.6%	4.1%	3.8%	3.8%	3.6%	3.2%	3.2%	2.9%	2.7%	3.4%	4.4%	5.0%	4.8%	4.1%	3.4%	3.3%	3.3%	3.5%	3.3%	3.2%	3.6%	5.1%	100.0%		

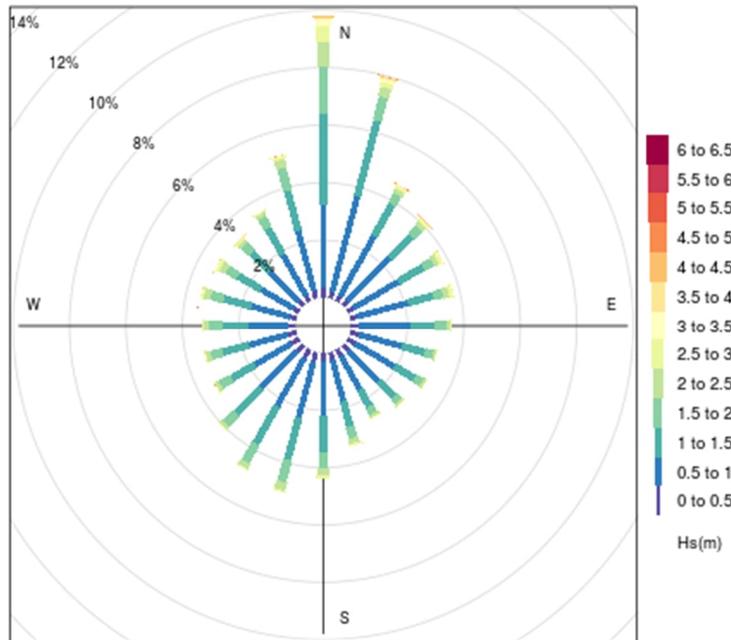


Plate A23. Wave Rose at Humber model boundary

Table A13. Selected directional sectors (degN) for swell waves

Selected sectors	From (°N)	To (°N)	'Central' direction for modelling (°N)
NE	7.5	67.5	45
E	67.5	112.5	90
SE	112.5	157.5	135

1.5.17 For the three direction sectors identified, extreme significant wave heights have been derived using the following approach:

- a. Independent storm peaks have been obtained from the time series of significant wave height. An independent storm peak is defined as having:
 - i. A minimum of 1-hour duration;
 - ii. A period of at least 24 hours between separate storm events, and;
 - iii. A height above a fixed Hs threshold.
- b. The selected Hs storm peaks are loaded into the Extreme Value Analysis (EVA) software.
- c. A Generalised Pareto Distribution (GPD) is fitted to the storm peaks and the shape and scale parameters of the fit determined;

- d. The Pareto fit to data is visually assessed and, if necessary, the storm peaks are reselected or the threshold varied, and the data refitted to improve the fit quality; and;
 - e. The final shape and scale parameters are used to extrapolate the theoretical fit to data in order to determine extreme return period events.
- 1.5.18 For each of the directional sectors, wave conditions have been derived for the following return periods:
- a. 1 in 0.5-year, and
 - b. 1 in 50-year
- 1.5.19 The resulting wave heights are presented in Table A14 and the Extreme Value Analysis plots associated with these values are provided in Plate A24 to Plate A26.
- 1.5.20 The spectral peak wave periods (T_p) provided in Table A14, were derived by an asymptotic steepness approximation. In higher sea states the wave steepness tends to become invariant with further increases in wave height. Therefore, estimations of wave steepness from the upper 50 sea states are identified and the 50th percentile of these was used to derive associated wave periods for the extreme significant wave heights. An example of the steepness relationship is shown in Plate A27.
- 1.5.21 Similarly, the wind conditions presented in Table A14, were determined by deriving a frequency table of wave height vs. wind speed for each of the direction sectors examined. For each of the extreme wave heights in Table A14 the associated, most frequently occurring, wind speed (to the nearest 2 m/s) was extracted from the frequency table.

Table A14. Extreme Boundary Wave Conditions for the Humber Spectral Wave Model

Return period (yr)		North-easterly	Easterly	South-easterly
		All Year	All Year	All Year
0.5	Hs (m)	3.4	2.4	2.4
	T_p (s)	9.0	6.7	5.6
	WS (m/s)	15.0	13.0	15.0
50	Hs (m)	5.2	4.1	4.8
	T_p (s)	11.1	8.7	7.9
	WS (m/s)	23.0	21.0	25.0

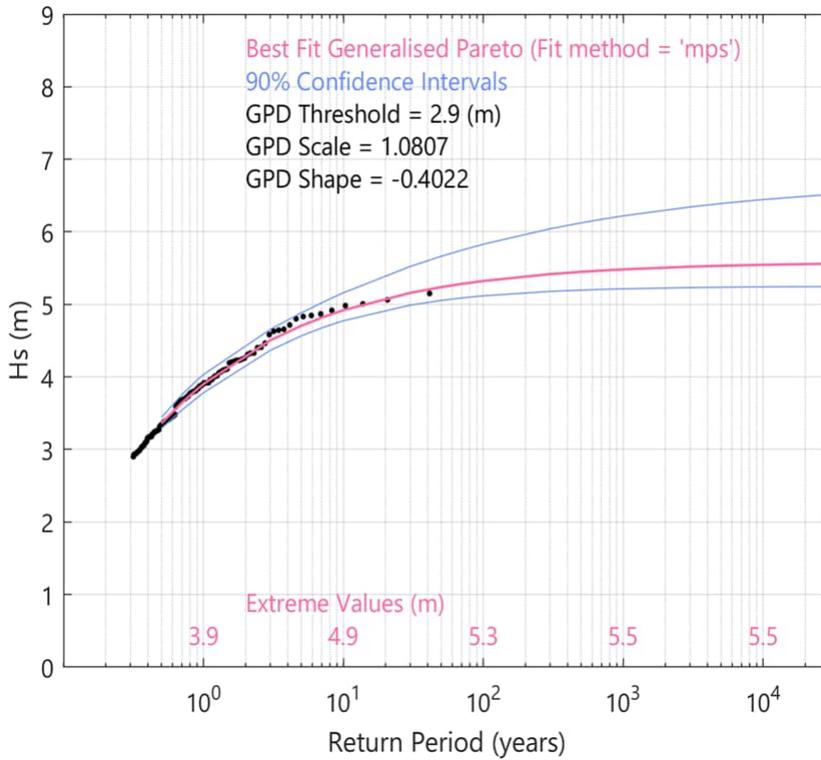


Plate A24. Extreme Hs GPD fit: Northeast All Year

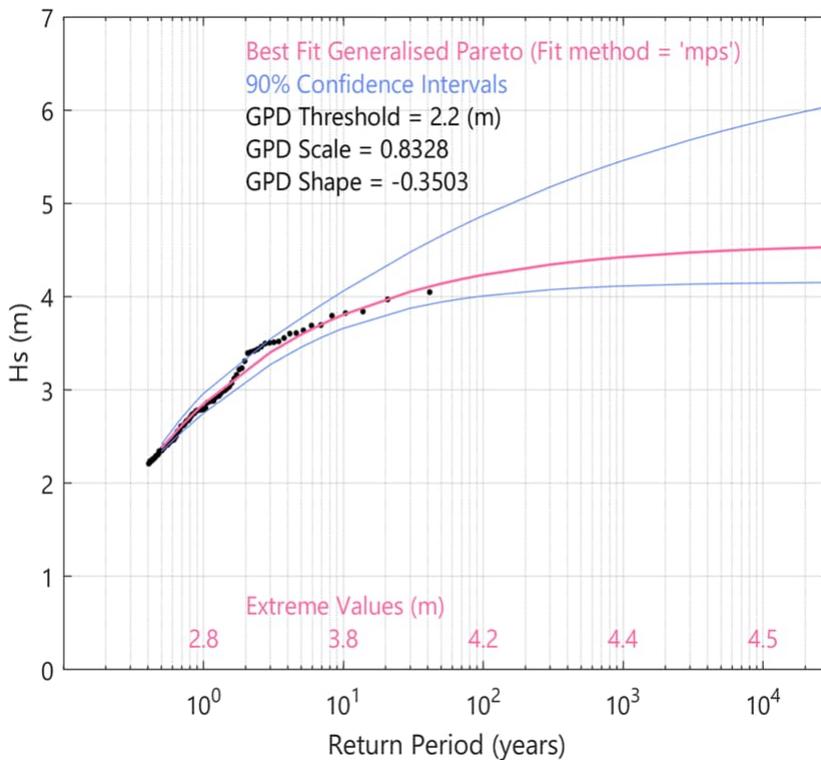


Plate A25. Extreme Hs GPD fit: East All Year

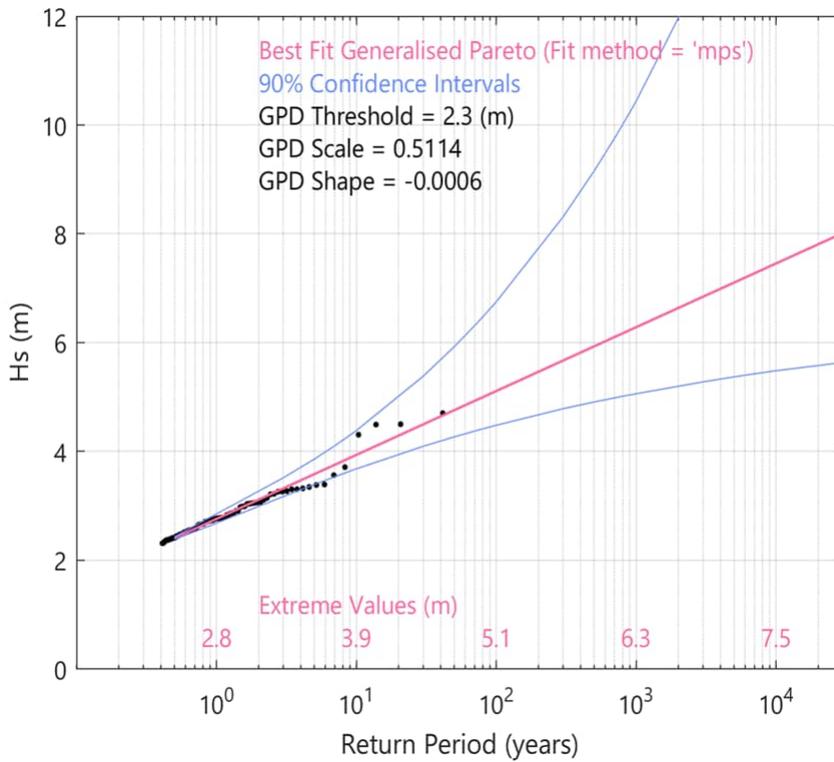


Plate A26. Extreme Hs GPD fit: Southeast All Year

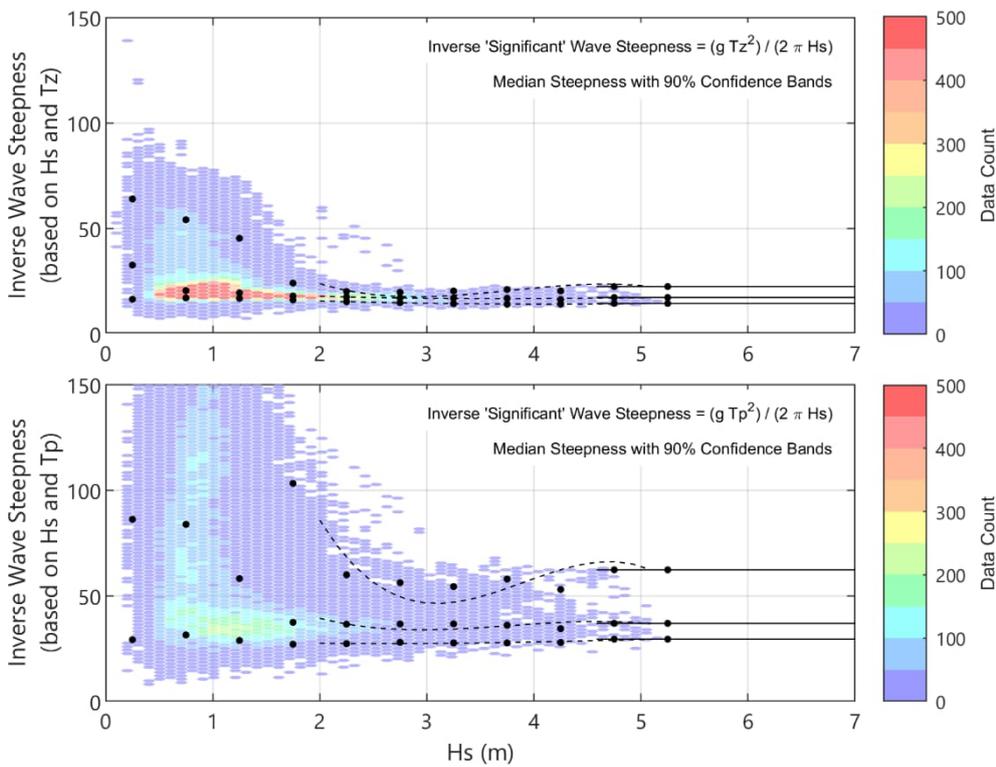


Plate A27. Asymptotic Wave Steepness: North East Sector, All Year condition

1.6 References

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